

ispLSI® and pLSI® 1016

High-Density Programmable Logic

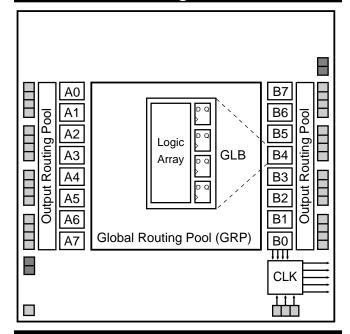
Features

- HIGH-DENSITY PROGRAMMABLE LOGIC
 - High-Speed Global Interconnect
 - 2000 PLD Gates
 - 32 I/O Pins, Four Dedicated Inputs
 - 96 Registers
 - Wide Input Gating for Fast Counters, State Machines, Address Decoders, etc.
 - Small Logic Block Size for Random Logic
 - Security Cell Prevents Unauthorized Copying
- HIGH PERFORMANCE E2CMOS® TECHNOLOGY
 - fmax = 110 MHz Maximum Operating Frequency
 - fmax = 60 MHz for Industrial and Military/883 Devices
 - tpd = 10 ns Propagation Delay
 - TTL Compatible Inputs and Outputs
 - Electrically Erasable and Reprogrammable
 - Non-Volatile E²CMOS Technology
 - 100% Tested
- ispLSI OFFERS THE FOLLOWING ADDED FEATURES
 - In-System Programmable™ (ISP™) 5-Volt Only
 - Increased Manufacturing Yields, Reduced Time-to-Market, and Improved Product Quality
 - Reprogram Soldered Devices for Faster Debugging
- COMBINES EASE OF USE AND THE FAST SYSTEM SPEED OF PLDs WITH THE DENSITY AND FLEX-IBILITY OF FIELD PROGRAMMABLE GATE ARRAYS
- Complete Programmable Device Can Combine Glue Logic and Structured Designs
- Three Dedicated Clock Input Pins
- Synchronous and Asynchronous Clocks
- Flexible Pin Placement
- Optimized Global Routing Pool Provides Global Interconnectivity
- ispLSI AND pLSI DEVELOPMENT TOOLS pDS® Software
 - Easy to Use PC Windows™ Interface
 - Boolean Logic Compiler
 - Manual Partitioning
 - Automatic Place and Route
 - Static Timing Table

pDS+™ Software

- Industry Standard, Third Party Design Environments
- Schematic Capture, State Machine, HDL
- Automatic Partitioning
- Automatic Place and Route
- Comprehensive Logic and Timing Simulation
- PC and Workstation Platforms

Functional Block Diagram



Description

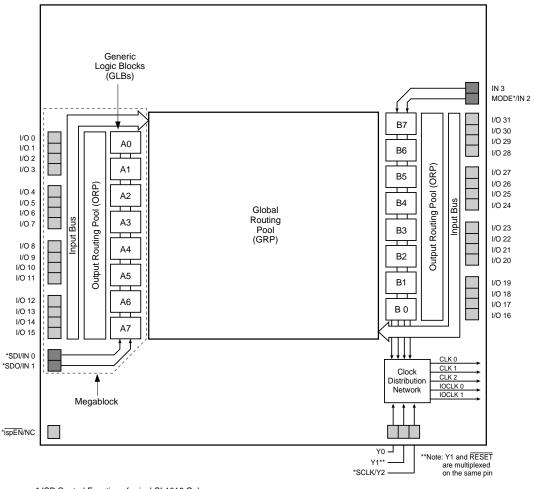
The ispLSI and pLSI 1016 are High-Density Programmable Logic Devices containing 96 Registers, 32 Universal I/O pins, four Dedicated Input pins, three Dedicated Clock Input pins and a Global Routing Pool (GRP). The GRP provides complete interconnectivity between all of these elements. The ispLSI 1016 features 5-Volt insystem programming and in-system diagnostic capabilities. It is the first device which offers non-volatile "on-the-fly" reprogrammability of the logic, as well as the interconnect to provide truly reconfigurable systems. It is architecturally and parametrically compatible to the pLSI 1016 device, but multiplexes four input pins to control insystem programming.

The basic unit of logic on the ispLSI and pLSI 1016 devices is the Generic Logic Block (GLB). The GLBs are labeled A0, A1.. B7 (see figure 1). There are a total of 16 GLBs in the ispLSI and pLSI 1016 devices. Each GLB has 18 inputs, a programmable AND/OR/XOR array, and four outputs which can be configured to be either combinatorial or registered. Inputs to the GLB come from the GRP and dedicated inputs. All of the GLB outputs are brought back into the GRP so that they can be connected to the inputs of any other GLB on the device.

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Functional Block Diagram

Figure 1. ispLSI and pLSI 1016 Functional Block Diagram



* ISP Control Functions for ispLSI 1016 Only

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The devices also have 32 I/O cells, each of which is directly connected to an I/O pin. Each I/O cell can be individually programmed to be a combinatorial input, registered input, latched input, output or bi-directional I/O pin with 3-state control. Additionally, all outputs are polarity selectable, active high or active low. The signal levels are TTL compatible voltages and the output drivers can source 4 mA or sink 8 mA.

Eight GLBs, 16 I/O cells, two dedicated inputs and one ORP are connected together to make a Megablock (see figure 1). The outputs of the eight GLBs are connected to a set of 16 universal I/O cells by the ORP. The ispLSI and pLSI 1016 devices contain two of these Megablocks.

The GRP has as its inputs the outputs from all of the GLBs and all of the inputs from the bi-directional I/O cells. All of these signals are made available to the inputs of the GLBs. Delays through the GRP have been equalized to minimize timing skew.

Clocks in the ispLSI and pLSI 1016 devices are selected using the Clock Distribution Network. Three dedicated clock pins (Y0, Y1 and Y2) are brought into the distribution network, and five clock outputs (CLK 0, CLK 1, CLK 2, IOCLK 0 and IOCLK 1) are provided to route clocks to the GLBs and I/O cells. The Clock Distribution Network can also be driven from a special clock GLB (B0 on the ispLSI and pLSI 1016 devices). The logic of this GLB allows the user to create an internal clock from a combination of internal signals within the device.



Absolute Maximum Ratings ¹

Supply Voltage V_{cc}-0.5 to +7.0V Input Voltage Applied-2.5 to V_{CC} +1.0V

Off-State Output Voltage Applied -2.5 to V_{CC} +1.0V

Storage Temperature-65 to 150°C

Case Temp. with Power Applied-55 to 125°C

Max. Junction Temp. (T_J) with Power Applied 150°C

DC Recommended Operating Conditions

| SYMBOL | PARAMETER | PARAMETER | | | MAX. | UNITS | |
|-------------|--------------------|--------------|------------------------------------------------|------|-----------------|-------|--|
| V cc | | Commercial | $T_A = 0$ °C to +70°C | 4.75 | 5.25 | | |
| | Supply Voltage | Industrial | $T_A = -40^{\circ}C$ to $+85^{\circ}C$ | 4.5 | 5.5 | V | |
| | | Military/883 | $T_C = -55^{\circ}C \text{ to } +125^{\circ}C$ | 4.5 | 5.5 | | |
| VIL | Input Low Voltage | | | 0 | 0.8 | V | |
| V IH | Input High Voltage | | | 2.0 | V cc + 1 | V | |

Table 2- 0005Aisp w/mil.eps

Capacitance (T_A=25°C, f=1.0 MHz)

| SYMBOL | PARAMETER | | MAXIMUM ¹ | UNITS | TEST CONDITIONS |
|----------------|-----------------------------|-----------------------|----------------------|-------|----------------------------------------------|
| C ₁ | Dedicated Input Capacitance | Commercial/Industrial | 8 | pf | V _{CC} =5.0V, V _{IN} =2.0V |
| | Dedicated Input Capacitance | Military | 10 | pf | V _{CC} =5.0V, V _{IN} =2.0V |
| C ₂ | I/O and Clock Capacitance | | 10 | pf | V_{CC} =5.0V, $V_{I/O}$, V_{Y} =2.0V |

^{1.} Guaranteed but not 100% tested.

Table 2- 0006

Data Retention Specifications

| PARAMETER | MINIMUM | MAXIMUM | UNITS |
|-------------------------------|---------|---------|--------|
| Data Retention | 20 | _ | Years |
| ispLSI Erase/Reprogram Cycles | 10000 | _ | Cycles |
| pLSI Erase/Reprogram Cycles | 100 | _ | Cycles |

Table 2- 0008B

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^{1.} Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. Functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

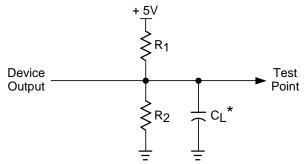


Switching Test Conditions

| Input Pulse Levels | GND to 3.0V |
|--------------------------------|------------------|
| Input Rise and Fall Time | ≤ 3ns 10% to 90% |
| Input Timing Reference Levels | 1.5V |
| Output Timing Reference Levels | 1.5V |
| Output Load | See figure 2 |

3-state levels are measured 0.5V from steady-state active level.

Figure 2. Test Load



*C_L includes Test Fixture and Probe Capacitance.

Output Load Conditions (see figure 2)

| Tes | t Condition | R1 | R2 | CL |
|-----|-----------------------------------------------------|------|------|------|
| Α | | 470Ω | 390Ω | 35pF |
| В | Active High | ∞ | 390Ω | 35pF |
| | Active Low | 470Ω | 390Ω | 35pF |
| С | Active High to Z at V _{OH} - 0.5V | ∞ | 390Ω | 5pF |
| | Active Low to Z at V _{OL} + 0.5V | 470Ω | 390Ω | 5pF |

Table 2- 0004A

DC Electrical Characteristics

Over Recommended Operating Conditions

| SYMBOL | PARAMETER | CONDIT | ION | MIN. | TYP. ³ | MAX. | UNITS |
|--------------------|-----------------------------------|-----------------------------------|---------------------|------|--------------------------|------|-------|
| V OL | Output Low Voltage | I _{OL} =8 mA | | _ | _ | 0.4 | V |
| V OH | Output High Voltage | I _{OH} =-4 mA | | 2.4 | _ | _ | V |
| I IL | Input or I/O Low Leakage Current | $0V \le V_{IN} \le V_{IL} (MAX.)$ | | _ | _ | -10 | μΑ |
| Iн | Input or I/O High Leakage Current | $3.5V \le V_{IN} \le V_{CC}$ | | _ | _ | 10 | μΑ |
| IL-isp | isp Input Low Leakage Current | $0V \le V_{IN} \le V_{IL} (MAX.)$ | | _ | _ | -150 | μΑ |
| I IL-PU | I/O Active Pull-Up Current | $0V \le V_{IN} \le V_{IL}$ | | _ | _ | -150 | μΑ |
| los1 | Output Short Circuit Current | $V_{CC} = 5V, V_{OUT} = 0.5V$ | | - | 1 | -200 | mA |
| ICC ^{2,4} | Operating Power Supply Current | $V_{IL} = 0.5V, V_{IH} = 3.0V$ | Commercial | _ | 100 | 150 | mA |
| | | $f_{TOGGLE} = 1 MHz$ | Industrial/Military | _ | 100 | 170 | mA |

- 1. One output at a time for a maximum duration of one second. V_{OUT} = 0.5V was selected to avoid test problems by tester ground degradation. Guaranteed but not 100% tested.
- 2. Measured using four 16-bit counters.
- 3. Typical values are at V_{CC} = 5V and T_A = 25°C.
- Maximum I_{CC} varies widely with specific device configuration and operating frequency. Refer to the Power Consumption section of this data sheet and Thermal Management section of this Data Book to estimate maximum I_{CC}.



External Timing Parameters

Over Recommended Operating Conditions

| PARAMETER | TEST 5 | # 2 | DESCRIPTION ¹ | -1 | 10 | -9 | 90 | UNITS |
|---------------------|--------|------------|----------------------------------------------------------|------|------|------|------|--------|
| ANAMETER | COND. | " | DEGGIN HON | MIN. | MAX. | MIN. | MAX. | 0.41.0 |
| t pd1 | Α | 1 | Data Propagation Delay, 4PT bypass, ORP bypass | - | 10 | _ | 12 | ns |
| t pd2 | Α | 2 | Data Propagation Delay, Worst Case Path | - | 14.5 | - | 17 | ns |
| f max (Int.) | Α | 3 | Clock Frequency with Internal Feedback ³ | 111 | 70 | 90.9 | - | MHz |
| f max (Ext.) | _ | 4 | Clock Frequency with External Feedback (1/(tsu2 + tco1)) | 70.1 | S | 58.8 | - | MHz |
| f max (Tog.) | _ | 5 | Clock Frequency, Max Toggle ⁴ | 125 | 5 | 125 | - | MHz |
| t su1 | _ | 6 | GLB Reg. Setup Time before Clock, 4PT bypass | 4.5 | 5 | 6 | - | ns |
| t co1 | Α | 7 | GLB Reg. Clock to Output Delay, ORP bypass | ti | 7 | - | 8 | ns |
| t h1 | _ | 8 | GLB Reg. Hold Time after Clock, 4 PT bypass | 0.0 | 0 | 0 | - | ns |
| t su2 | _ | 9 | GLB Reg. Setup Time before Clock | 7.5 | 7 | 9 | - | ns |
| t co2 | _ | 10 | GLB Reg. Clock to Output Delay | 15 | 8.5 | - | 10 | ns |
| t h2 | _ | 11 | GLB Reg. Hold Time after Clock | 0 | 7 | 0 | - | ns |
| t r1 | Α | 12 | Ext. Reset Pin to Output Delay | 5 | 14 | _ | 15 | ns |
| t rw1 | _ | 13 | Ext. Reset Pulse Duration | 10 | K- | 10 | - | ns |
| t en | В | 14 | Input to Output Enable | - | 15 | _ | 15 | ns |
| t dis | С | 15 | Input to Output Disable | - ' | 15 | _ | 15 | ns |
| t wh | _ | 16 | Ext. Sync. Clock Pulse Duration, High | 4 | - | 4 | _ | ns |
| twl | _ | 17 | Ext. Sync. Clock Pulse Duration, Low | 4 | - | 4 | _ | ns |
| t su5 | _ | 18 | I/O Reg. Setup Time before Ext. Sync. Clock (Y1, Y2) | 2 | - | 2 | - | ns |
| t h5 | _ | 19 | I/O Reg. Hold Time after Ext. Sync. Clock (Y1, Y2) | 5.5 | _ | 6.5 | _ | ns |

- 1. Unless noted otherwise, all parameters use a GRP load of 4 GLBs, 20 PTXOR path, ORP and Y0 clock.
- 2. Refer to Timing Model in this data sheet for further details.
- 3. Standard 16-bit loadable counter using GRP feedback.
- 4. fmax (Toggle) may be less than 1/(twh + twl). This is to allow for a clock duty cycle of other than 50%.
- 5. Reference Switching Test Conditions section.



External Timing Parameters

Over Recommended Operating Conditions

| PARAMETER | TEST 5 | # 2 | DESCRIPTION ¹ | | 80 | -6 | 60 | UNITS |
|---------------------|--------|------------|----------------------------------------------------------|------|------|------|------|--------|
| ANAMETER | COND. | " | DEGGKII TION | MIN. | MAX. | MIN. | MAX. | Oitilo |
| t pd1 | Α | 1 | Data Propagation Delay, 4PT bypass, ORP bypass | _ | 15 | _ | 20 | ns |
| t pd2 | Α | 2 | Data Propagation Delay, Worst Case Path | _ | 20 | _ | 25 | ns |
| f max (Int.) | Α | 3 | Clock Frequency with Internal Feedback ³ | 80 | _ | 60 | _ | MHz |
| f max (Ext.) | _ | 4 | Clock Frequency with External Feedback (1/(tsu2 + tco1)) | 50 | _ | 38 | _ | MHz |
| f max (Tog.) | _ | 5 | Clock Frequency, Max Toggle ⁴ | 100 | _ | 83 | _ | MHz |
| t su1 | _ | 6 | GLB Reg. Setup Time before Clock, 4PT bypass | 7 | _ | 9 | _ | ns |
| t co1 | Α | 7 | GLB Reg. Clock to Output Delay, ORP bypass | - | 10 | _ | 13 | ns |
| t h1 | - | 8 | GLB Reg. Hold Time after Clock, 4 PT bypass | 0 | - | 0 | _ | ns |
| t su2 | - | 9 | GLB Reg. Setup Time before Clock | 10 | - | 13 | _ | ns |
| t co2 | - | 10 | GLB Reg. Clock to Output Delay | _ | 12 | _ | 16 | ns |
| t h2 | _ | 11 | GLB Reg. Hold Time after Clock | 0 | _ | 0 | _ | ns |
| t r1 | Α | 12 | Ext. Reset Pin to Output Delay | _ | 17 | _ | 22.5 | ns |
| t rw1 | _ | 13 | Ext. Reset Pulse Duration | 10 | _ | 13 | _ | ns |
| t en | В | 14 | Input to Output Enable | _ | 18 | _ | 24 | ns |
| t dis | С | 15 | Input to Output Disable | _ | 18 | _ | 24 | ns |
| t wh | _ | 16 | Ext. Sync. Clock Pulse Duration, High | 5 | _ | 6 | _ | ns |
| twl | _ | 17 | Ext. Sync. Clock Pulse Duration, Low | 5 | _ | 6 | _ | ns |
| t su5 | _ | 18 | I/O Reg. Setup Time before Ext. Sync. Clock (Y1, Y2) | 2 | _ | 2.5 | _ | ns |
| t h5 | _ | 19 | I/O Reg. Hold Time after Ext. Sync. Clock (Y1, Y2) | 6.5 | _ | 8.5 | _ | ns |

- 1. Unless noted otherwise, all parameters use a GRP load of 4 GLBs, 20 PTXOR path, ORP and Y0 clock.
- 2. Refer to Timing Model in this data sheet for further details.
- 3. Standard 16-Bit loadable counter using GRP feedback.
- 4. fmax (Toggle) may be less than 1/(twh + twl). This is to allow for a clock duty cycle of other than 50%.
- 5. Reference Switching Test Conditions section.



| DADAMETER | # ² | DESCRIPTION | -1 | 10 | -9 | 1.0 n 2.0 n - n 2.0 n 2.5 n 2.0 n 1.0 n 2.6 n 3.4 n | UNITS |
|------------------|-----------------------|--------------------------------------------------|-------|------|------|-----------------------------------------------------|-------|
| PARAMETER | # | DESCRIPTION | MIN. | MAX. | MIN. | MAX. | UNITS |
| Inputs | | | - | | | | |
| tiobp | 20 | I/O Register Bypass | _ | 0.8 | _ | 1.0 | ns |
| t iolat | 21 | I/O Latch Delay | _ | 1.7 | _ | 2.0 | ns |
| t iosu | 22 | I/O Register Setup Time before Clock | 4.1 | (A) | 4.5 | _ | ns |
| t ioh | 23 | I/O Register Hold Time after Clock | 1.8 | Z | 2.0 | - | ns |
| t ioco | 24 | I/O Register Clock to Out Delay | _ | 4.7 | _ | 2.0 | ns |
| t ior | 25 | I/O Register Reset to Out Delay | _ | (2)1 | _ | 2.5 | ns |
| t din | 26 | Dedicated Input Delay | _ | 11.7 | _ | 2.0 | ns |
| GRP | | | | | | | |
| t grp1 | 27 | GRP Delay, 1 GLB Load | _ | 0.6 | _ | 0.7 | ns |
| t grp4 | 28 | GRP Delay, 4 GLB Loads | _ | 0.8 | _ | 1.0 | ns |
| t grp8 | 29 | GRP Delay, 8 GLB Loads | _ 1 | 1.5 | _ | 1.8 | ns |
| t grp12 | 30 | GRP Delay, 12 GLB Loads | - 1 | 2.1 | _ | 2.6 | ns |
| t grp16 | 31 | GRP Delay, 16 GLB Loads | - (| 2.8 | _ | 3.4 | ns |
| GLB | | | | _ | | | |
| t 4ptbp | 33 | 4 Product Term Bypass Path Delay | 1 - 8 | 5.3 | _ | 6.5 | ns |
| t 1ptxor | 34 | 1 Product Term/XOR Path Delay | | 6.1 | _ | 7.0 | ns |
| t 20ptxor | 35 | 20 Product Term/XOR Path Delay | ٦. | 6.6 | _ | 8.0 | ns |
| t xoradj | 36 | XOR Adjacent Path Delay ³ | 7 | 8.2 | _ | 9.5 | ns |
| t gbp | 37 | GLB Register Bypass Delay | + | 0.5 | _ | 0.5 | ns |
| t gsu | 38 | GLB Register Setup Time before Clock | 0.3 | _ | 1.0 | _ | ns |
| t gh | 39 | GLB Register Hold Time after Clock | 2.9 | _ | 3.5 | _ | ns |
| t gco | 40 | GLB Register Clock to Output Delay | Ц | 1.6 | - | 1.5 | ns |
| t gr | 41 | GLB Register Reset to Output Delay | 75 | 2.1 | _ | 2.5 | ns |
| t ptre | 42 | GLB Product Term Reset to Register Delay |)- | 8.2 | _ | 10.0 | ns |
| t ptoe | 43 | GLB Product Term Output Enable to I/O Cell Delay | _ | 9.0 | - | 9.0 | ns |
| t ptck | 44 | GLB Product Term Clock Delay | 2.8 | 6.2 | 3.5 | 7.5 | ns |
| ORP | | | | | | | |
| t orp | 45 | ORP Delay | - | 2.0 | _ | 2.5 | ns |
| t orpbp | 46 | ORP Bypass Delay | _ | 0.4 | _ | 0.5 | ns |

^{1.} Internal Timing Parameters are not tested and are for reference only.

^{2.} Refer to Timing Model in this data sheet for further details.

^{3.} The XOR adjacent path can only be used by hard macros.



| PARAMETER | # ² | DESCRIPTION | -110 | -9 | 90 | UNITS |
|-----------------|-----------------------|-------------------------------------------------------|-----------|------|------|-----------|
| PARAMETER | # | DESCRIPTION | MIN. MAX. | MIN. | MAX. | • • • • • |
| Outputs | | | οZ | | • | |
| t ob | 47 | Output Buffer Delay | | _ | 2.5 | ns |
| t oen | 48 | I/O Cell OE to Output Enabled | - (3,3 | - | 4.0 | ns |
| t odis | 49 | I/O Cell OE to Output Disabled | 3.3 | - | 4.0 | ns |
| Clocks | | | 190 | | • | |
| t gy0 | 50 | Clock Delay, Y0 to Global GLB Clock Line (Ref. clock) | 2.9 2.9 | 3.5 | 3.5 | ns |
| t gy1/2 | 51 | Clock Delay, Y1 or Y2 to Global GLB Clock Line | 2.1 3.8 | 2.5 | 4.5 | ns |
| t gcp | 52 | Clock Delay, Clock GLB to Global GLB Clock Line | 0.8 4.2 | 1.0 | 5.0 | ns |
| t ioy1/2 | 53 | Clock Delay, Y1 or Y2 to I/O Cell Global Clock Line | 2.1 1 3.8 | 2.5 | 4.5 | ns |
| tiocp | 54 | Clock Delay, Clock GLB to I/O Cell Global Clock Line | 0.8 4.2 | 1.0 | 5.0 | ns |
| Global Re | set | | L | | | |
| t gr | 55 | Global Reset to GLB and I/O Registers | - 7.9 | _ | 7.5 | ns |

^{1.} Internal Timing Parameters are not tested and are for reference only.

^{2.} Refer to Timing Model in this data sheet for further details.



| | # ² | DESCRIPTION | -8 | 30 | -(| 60 | UNITS |
|------------------|-----------------------|--------------------------------------------------|------|------|------|------|----------|
| PARAMETER | # | DESCRIPTION | MIN. | MAX. | MIN. | MAX. | UNITS |
| Inputs | | | | | | 1 | <u> </u> |
| tiobp | 20 | I/O Register Bypass | _ | 2.0 | _ | 2.7 | ns |
| t iolat | 21 | I/O Latch Delay | _ | 3.0 | _ | 4.0 | ns |
| t iosu | 22 | I/O Register Setup Time before Clock | 5.5 | _ | 7.3 | _ | ns |
| t ioh | 23 | I/O Register Hold Time after Clock | 1.0 | - | 1.3 | _ | ns |
| t ioco | 24 | I/O Register Clock to Out Delay | _ | 3.0 | _ | 4.0 | ns |
| t ior | 25 | I/O Register Reset to Out Delay | _ | 2.5 | _ | 3.3 | ns |
| t din | 26 | Dedicated Input Delay | _ | 4.0 | _ | 5.3 | ns |
| GRP | | | | | • | | • |
| t grp1 | 27 | GRP Delay, 1 GLB Load | - | 1.5 | _ | 2.0 | ns |
| t grp4 | 28 | GRP Delay, 4 GLB Loads | _ | 2.0 | _ | 2.7 | ns |
| t grp8 | 29 | GRP Delay, 8 GLB Loads | _ | 3.0 | _ | 4.0 | ns |
| t grp12 | 30 | GRP Delay, 12 GLB Loads | _ | 3.8 | _ | 5.0 | ns |
| t grp16 | 31 | GRP Delay, 16 GLB Loads | _ | 4.5 | _ | 6.0 | ns |
| GLB | | | - | | | | |
| t 4ptbp | 33 | 4 Product Term Bypass Path Delay | _ | 6.5 | - | 8.6 | ns |
| t 1ptxor | 34 | 1 Product Term/XOR Path Delay | _ | 7.0 | _ | 9.3 | ns |
| t 20ptxor | 35 | 20 Product Term/XOR Path Delay | _ | 8.0 | _ | 10.6 | ns |
| t xoradj | 36 | XOR Adjacent Path Delay ³ | _ | 9.5 | _ | 12.7 | ns |
| t gbp | 37 | GLB Register Bypass Delay | _ | 1.0 | _ | 1.3 | ns |
| t gsu | 38 | GLB Register Setup Time before Clock | 1.0 | _ | 1.3 | _ | ns |
| t gh | 39 | GLB Register Hold Time after Clock | 4.5 | _ | 6.0 | _ | ns |
| t gco | 40 | GLB Register Clock to Output Delay | _ | 2.0 | _ | 2.7 | ns |
| t gr | 41 | GLB Register Reset to Output Delay | _ | 2.5 | _ | 3.3 | ns |
| t ptre | 42 | GLB Product Term Reset to Register Delay | _ | 10.0 | _ | 13.3 | ns |
| t ptoe | 43 | GLB Product Term Output Enable to I/O Cell Delay | _ | 9.0 | _ | 12.0 | ns |
| t ptck | 44 | GLB Product Term Clock Delay | 3.5 | 7.5 | 4.6 | 9.9 | ns |
| ORP | | | | | | | |
| t orp | 45 | ORP Delay | _ | 2.5 | _ | 3.3 | ns |
| t orpbp | 46 | ORP Bypass Delay | _ | 0.5 | _ | 0.7 | ns |

 $^{{\}bf 1.}\ \ {\bf Internal\ Timing\ Parameters\ are\ not\ tested\ and\ are\ for\ reference\ only.}$

^{2.} Refer to Timing Model in this data sheet for further details.

^{3.} The XOR Adjacent path can only be used by Hard Macros.

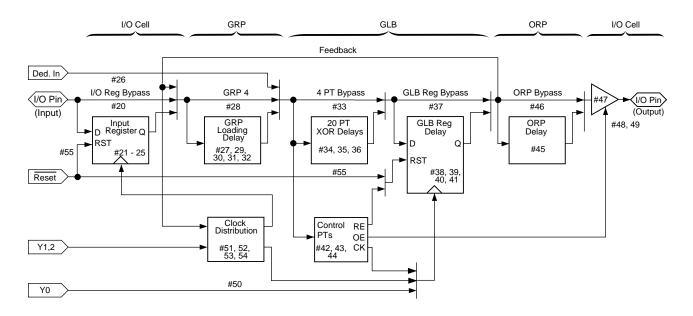


| PARAMETER | # ² | DESCRIPTION | | 30 | -6 | 0 | UNITS |
|-----------------|-----------------------|-------------------------------------------------------|------|------|------|------|-------|
| PARAIVIETER | # | DESCRIPTION | MIN. | MAX. | MIN. | MAX. | |
| Outputs | | | | | | | |
| t ob | 47 | Output Buffer Delay | _ | 3.0 | _ | 4.0 | ns |
| t oen | 48 | I/O Cell OE to Output Enabled | _ | 5.0 | _ | 6.7 | ns |
| t odis | 49 | I/O Cell OE to Output Disabled | _ | 5.0 | _ | 6.7 | ns |
| Clocks | | | | | | | |
| t gy0 | 50 | Clock Delay, Y0 to Global GLB Clock Line (Ref. clock) | 4.5 | 4.5 | 6.0 | 6.0 | ns |
| t gy1/2 | 51 | Clock Delay, Y1 or Y2 to Global GLB Clock Line | 3.5 | 5.5 | 4.6 | 7.3 | ns |
| t gcp | 52 | Clock Delay, Clock GLB to Global GLB Clock Line | 1.0 | 5.0 | 1.3 | 6.6 | ns |
| t ioy1/2 | 53 | Clock Delay, Y1 or Y2 to I/O Cell Global Clock Line | 3.5 | 5.5 | 4.6 | 7.3 | ns |
| tiocp | 54 | Clock Delay, Clock GLB to I/O Cell Global Clock Line | 1.0 | 5.0 | 1.3 | 6.6 | ns |
| Global Re | set | | | | | | |
| t gr | 55 | Global Reset to GLB and I/O Registers | _ | 9.0 | _ | 12.0 | ns |

^{1.} Internal Timing Parameters are not tested and are for reference only.

^{2.} Refer to Timing Model in this data sheet for further details.

ispLSI and pLSI 1016 Timing Model



Derivations of tsu, th and tco from the Product Term Clock¹

```
tsu = Logic + Reg su - Clock (min)

= (\mathbf{t}iobp + \mathbf{t}grp4 + \mathbf{t}20ptxor) + (\mathbf{t}gsu) - (\mathbf{t}iobp + \mathbf{t}grp4 + \mathbf{t}ptck(min))

= (\#20 + \#28 + \#35) + (\#38) - (\#20 + \#28 + \#44)

5.5 ns = (1.0 + 1.0 + 8.0) + (1.0) - (1.0 + 1.0 + 3.5)

th = Clock (max) + Reg h - Logic

= (\mathbf{t}iobp + \mathbf{t}grp4 + \mathbf{t}ptck(max)) + (\mathbf{t}gh) - (\mathbf{t}iobp + \mathbf{t}grp4 + \mathbf{t}20ptxor)

= (\#20 + \#28 + \#44) + (\#39) - (\#20 + \#28 + \#35)

3.0 ns = (1.0 + 1.0 + 7.5) + (3.5) - (1.0 + 1.0 + 8.0)

tco = Clock (max) + Reg co + Output

= (\mathbf{t}iobp + \mathbf{t}grp4 + \mathbf{t}ptck(max)) + (\mathbf{t}gco) + (\mathbf{t}orp + \mathbf{t}ob)

= (\#20 + \#28 + \#44) + (\#40) + (\#45 + \#47)

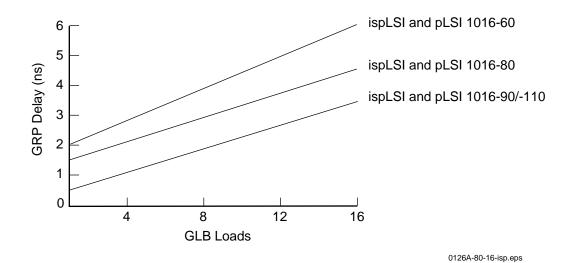
16.0 ns = (1.0 + 1.0 + 7.5) + (1.5) + (2.5 + 2.5)
```

Derivations of tsu, th and tco from the Clock GLB¹

```
\begin{array}{lll} \textbf{tsu} &=& \text{Logic} + \text{Reg su} - \text{Clock (min)} \\ &=& \left( \textbf{tiobp} + \textbf{t} \text{grp4} + \textbf{t} \text{20ptxor} \right) + \left( \textbf{tgsu} \right) - \left( \textbf{tgy0(min)} + \textbf{tgco} + \textbf{tgcp(min)} \right) \\ &=& \left( \#20 + \#28 + \#35 \right) + \left( \#38 \right) - \left( \#50 + \#40 + \#52 \right) \\ 5.0 \, \text{ns} &=& \left( 1.0 + 1.0 + 8.0 \right) + \left( 1.0 \right) - \left( 3.5 + 1.5 + 1.0 \right) \\ \textbf{th} &=& \text{Clock (max)} + \text{Reg h} - \text{Logic} \\ &=& \left( \textbf{tgy0(max)} + \textbf{tgco} + \textbf{tgcp(max)} \right) + \left( \textbf{tgh} \right) - \left( \textbf{tiobp} + \textbf{tgrp4} + \textbf{t} \text{20ptxor} \right) \\ &=& \left( \#50 + \#40 + \#52 \right) + \left( \#39 \right) - \left( \#20 + \#28 + \#35 \right) \\ 3.5 \, \text{ns} &=& \left( 3.5 + 1.5 + 5.0 \right) + \left( 3.5 \right) - \left( 1.0 + 1.0 + 8.0 \right) \\ \textbf{tco} &=& \text{Clock (max)} + \text{Reg co} + \text{Output} \\ &=& \left( \textbf{tgy0(max)} + \textbf{tgco} + \textbf{tgcp(max)} \right) + \left( \textbf{tgco} \right) + \left( \textbf{torp} + \textbf{tob} \right) \\ &=& \left( \#50 + \#40 + \#52 \right) + \left( \#40 \right) + \left( \#45 + \#47 \right) \\ 16.5 \, \text{ns} &=& \left( 3.5 + 1.5 + 5.0 \right) + \left( 1.5 \right) + \left( 2.5 + 2.5 \right) \\ \end{array}
```

1. Calculations are based upon timing specifications for the ispLSI and pLSI 1016-90.

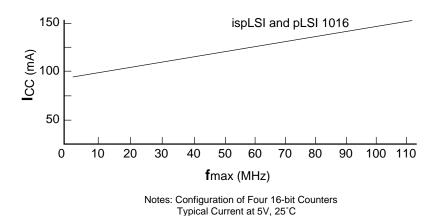
Maximum GRP Delay vs GLB Loads



Power Consumption

Power consumption in the ispLSI and pLSI 1016 device depends on two primary factors: the speed at which the device is operating, and the number of Product Terms used. Figure 3 shows the relationship between power and operating speed.

Figure 3. Typical Device Power Consumption vs fmax



ICC can be estimated for the ispLSI and pLSI 1016 using the following equation:

ICC = 31 + (# of PTs * 0.45) + (# of nets * Max. freq * 0.009) where: # of PTs = Number of Product Terms used in design

of nets = Number of Signals used in device

Max. freq = Highest Clock Frequency to the device

The I_{CC} estimate is based on typical conditions ($V_{CC} = 5.0V$, room temperature) and an assumption of 2 GLB loads on average exists. These values are for estimates only. Since the value of I_{CC} is sensitive to operating conditions and the program in the device, the actual I_{CC} should be verified.

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In-System Programmability

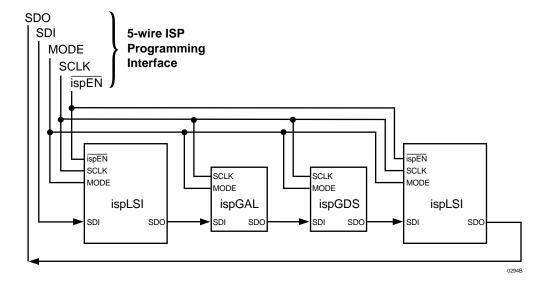
The ispLSI devices are the in-system programmable versions of the Lattice Semiconductor High-Density programmable Large Scale Integration (pLSI) devices. By integrating all the high voltage programming circuitry onchip, programming can be accomplished by simply shifting data into the device. Once the function is programmed, the non-volatile E²CMOS cells will not lose the pattern even when the power is turned off.

All necessary programming is done via five TTL level logic interface signals. These five signals are fed into the on-chip programming circuitry where a state machine

controls the programming. The interface signals are isp Enable (ispEN), Serial Data In (SDI), Serial Data Out (SDO), Serial Clock (SCLK) and Mode (MODE) control. Figure 4 illustrates the block diagram of one possible scheme for programming the ispLSI devices. For details on the operation of the internal state machine and programming of the device please refer to the ISP Architecture and Programming section in this Data Book.

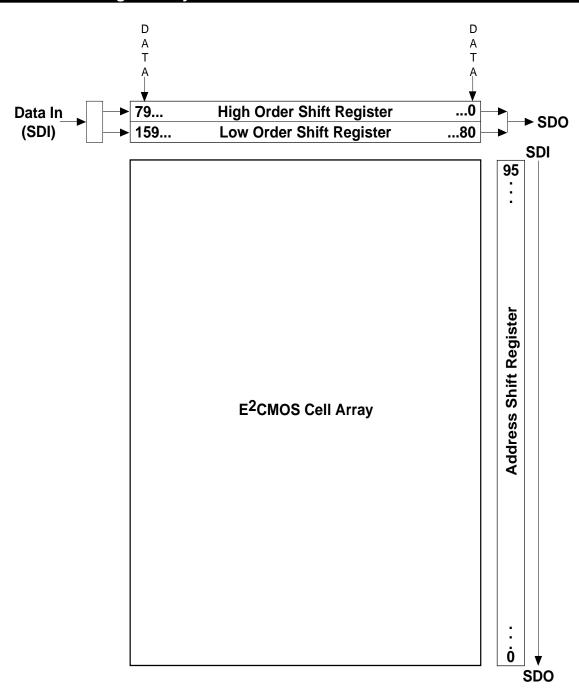
The device identifier for the ispLSI 1016 is 0000 0001 (01 hex). This code is the unique device identifier which is generated when a read ID command is performed.

Figure 4. ISP Programming Interface



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ispLSI 1016 Shift Register Layout



Note: A logic "1" in the Address Shift Register bit position enables the row for programming or verification. A logic "0" disables it.



Pin Description

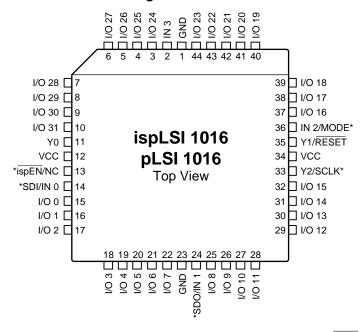
| NAME | PLCC PIN NUMBERS | TQFP PIN NUMBERS | JLCC PIN NUMBERS | DESCRIPTION |
|-------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| I/O 0 - I/O 3 I/O 4 - I/O 7 I/O 8 - I/O 11 I/O 12 - I/O 15 I/O 16 - I/O 19 I/O 20 - I/O 23 I/O 24 - I/O 27 I/O 28 - I/O 31 | 15, 16, 17, 18, 19, 20, 21, 22, 25, 26, 27, 28, 29, 30, 31, 32, | 9, 10, 11, 12, 13, 14, 15, 16, 19, 20, 21, 22, 23, 24, 25, 26, 31, 32, 33, 34, 35, 36, 37, 38, 41, 42, 43, 44, | 15, 16, 17, 18, 19, 20, 21, 22, 25, 26, 27, 28, 29, 30, 31, 32, 37, 38, 39, 40, 41, 42, 43, 44, | Input/Output Pins - These are the general purpose I/O pins used by the logic array. |
| IN 3 | 2 | 40 | 2 | Dedicated input pins to the device. |
| ispEN*/NC | 13 | 7 | 13 | Input – Dedicated in-system programming enable input pin. This pin is brought low to enable the programming mode. The MODE, SDI, SDO and SCLK options become active. |
| SDI*/IN 0 | 14 | 8 | 14 | Input – This pin performs two functions. It is a dedicated input pin when ispEN is logic high. When ispEN is logic low, it functions as an input pin to load programming data into the device. SDI/IN 0 also is used as one of the two control pins for the isp state machine. |
| MODE*/IN 2 | 36 | 30 | 36 | Input – This pin performs two functions. It is a dedicated input pin when ispEN is logic high. When ispEN is logic low, it functions as a pin to control the operation of the isp state machine. |
| SDO*/IN 1 | 24 | 18 | 24 | Input/Output – This pin performs two functions. It is a dedicated input pin when ispEN is logic high. When ispEN is logic low, it functions as an output pin to read serial shift register data. |
| SCLK*/Y2 | 33 | 27 | 33 | Input — This pin performs two functions. It is a dedicated clock input when ispEN is logic high. This clock input is brought into the Clock Distribution Network, and can optionally be routed to any GLB and/or I/O cell on the device. When ispEN is logic low, it functions as a clock pin for the Serial Shift Register. |
| Y0 | 11 | 5 | 11 | Dedicated Clock input. This clock input is connected to one of the clock inputs of all of the GLBs on the device. |
| Y1/RESET | 35 | 29 | 35 | This pin performs two functions: |
| | | | | Dedicated clock input. This clock input is brought into the Clock Distribution Network, and can optionally be routed to any GLB and/or I/O cell on the device. Active Low (0) Reset pin which resets all of the GLB and I/O registers in the device. |
| GND VCC | 11, 23 12, 34 | 7, 39 6, 28 | 1, 23 12, 34 | Ground (GND) V _{cc} |

^{*} For ispLSI 1016 Only

Table 2 - 0002C-16-isp

Pin Configuration

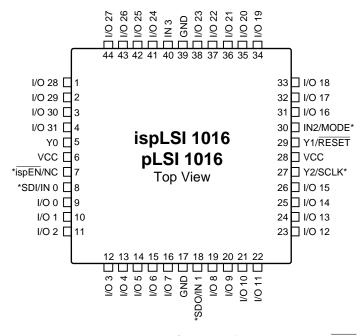
ispLSI and pLSI 1016 44-Pin PLCC Pinout Diagram



^{*} Pins have dual function capability for ispLSI 1016 only (except pin 13, which is ispEN only).

0123A-isp1016

ispLSI and pLSI 1016 44-Pin TQFP Pinout Diagram

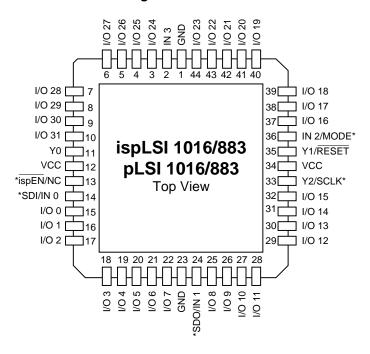


^{*} Pins have dual function capability for ispLSI 1016 only (except pin 7, which is ispEN only).

0851-16/TQF

Pin Configuration

ispLSI and pLSI 1016 44-Pin JLCC Pinout Diagram

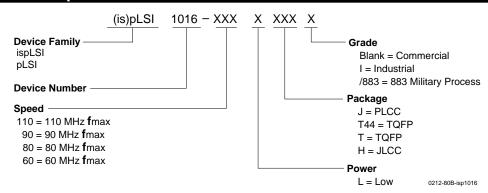


^{*} Pins have dual function capability for ispLSI 1016 only (except pin 13, which is ispEN only).

0123-16-isp/JLCC



Part Number Description



ispLSI and pLSI 1016 Ordering Information

COMMERCIAL

| Family | f max (MHz) | tpd (ns) | Ordering Number | Package |
|--------|--------------------|----------|--------------------|-------------|
| | 110 | 10 | ispLSI 1016-110LJ | 44-Pin PLCC |
| | 90 | 12 | ispLSI 1016-90LJ | 44-Pin PLCC |
| | 90 | 12 | ispLSI 1016-90LT44 | 44-Pin TQFP |
| | 90 | 12 | ispLSI 1016-90LT | 44-Pin TQFP |
| ispLSI | 80 | 15 | ispLSI 1016-80LJ | 44-Pin PLCC |
| | 80 | 15 | ispLSI 1016-80LT44 | 44-Pin TQFP |
| | 80 | 15 | ispLSI 1016-80LT | 44-Pin TQFP |
| | 60 | 20 | ispLSI 1016-60LJ | 44-Pin PLCC |
| | 60 | 20 | ispLSI 1016-60LT44 | 44-Pin TQFP |
| | 60 | 20 | ispLSI 1016-60LT | 44-Pin TQFP |
| | 110 | 10 | pLSI 1016-110LJ | 44-Pin PLCC |
| | 90 | | pLSI 1016-90LJ | 44-Pin PLCC |
| | 90 | 12 | pLSI 1016-90LT44 | 44-Pin TQFP |
| pLSI | 90 | 12 | pLSI 1016-90LT | 44-Pin TQFP |
| | 80 | 15 | pLSI 1016-80LJ | 44-Pin PLCC |
| | 80 | 15 | pLSI 1016-80LT44 | 44-Pin TQFP |
| | 80 | 15 | pLSI 1016-80LT | 44-Pin TQFP |
| | 60 | 20 | pLSI 1016-60LJ | 44-Pin PLCC |
| | 60 | 20 | pLSI 1016-60LT44 | 44-Pin TQFP |
| | 60 | 20 | pLSI 1016-60LT | 44-Pin TQFP |

INDUSTRIAL

| Family | f max (MHz) | tpd (ns) | Ordering Number | Package |
|--------|--------------------|----------|---------------------|-------------|
| ispLSI | 60 | 20 | ispLSI 1016-60LJI | 44-Pin PLCC |
| ispcoi | 60 | 20 | ispLSI 1016-60LT44I | 44-Pin TQFP |
| pLSI | 60 | 20 | pLSI 1016-60LJI | 44-Pin PLCC |

MILITARY/883

| Family | f max (MHz) | t pd (ns) | Ordering Number | SMD# | Package |
|--------|--------------------|------------------|----------------------|-----------------|-------------|
| ispLSI | 60 | 20 | ispLSI 1016-60LH/883 | 5962-9476201MXC | 44-Pin JLCC |
| pLSI | 60 | 20 | pLSI 1016-60LH/883 | 5962-9476301MXC | 44-Pin JLCC |

Note: Lattice Semiconductor recognizes the trend in military device procurement towards using SMD compliant devices, as such, ordering by this number is recommended.

Table 2-0041-16-isp1016

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