Section 3. BIOS Data Areas

The BIOS data areas are allocated specifically as work areas for system BIOS and adapter BIOS. The BIOS routines use 256 bytes of memory from absolute address hex 400 to hex 4FF. A description of the BIOS data areas follows.

Addre (Hex)	Function	Size
40:00	RS-232C communication line 1 port base address	Word
40:02	RS-232C communication line 2 port base address	Word
40:04	RS-232C communication line 3 port base address	Word
40:06	RS-232C communication line 4 port base address	Word
Note:	The RS-232C communication line port base address fields can be initialized to 0 by the POST if the system configuration contains less than four serial ports. The POST never puts 0 in the RS-232C communication line port base address table between two valid RS-232C communication line port base addresses.	

Figure 3-1. RS-232C Port Base Address Data Area

Address (Hex)	Function	Size
. ,		0.20
40:08	Printer 1 port base address	Word
40:0A	Printer 2 port base address	Word
40:0C	Printer 3 port base address	Word
40:0E	Reserved	Word
Exception: 40:0E	Printer 4 port base address (PC, PC/XT, AT, and PC Convertible)	Word
the syste never pu	The printer port base address fields can be initialized to 0 by the POST if the system configuration contains less than four parallel ports. The POST never puts 0 in the printer port base address table between two valid printer port base addresses.	

Figure 3-2. Printer Port Base Address Data Area

Address (Hex)	Function	Size
40:10	Installed hardware	Word
Bits 15, 14	Number of printer adapters	
Bit 13	Reserved	
Bit 12	Reserved	
Bits 11 to 9	Number of RS-232C adapters	
Bit 8	Reserved	
Bits 7, 6	Number of diskette drives (0-based)	
Bits 5, 4	Video mode type (values are binary)	
	= 00 - Reserved	
	= 01 - 40x25 color	
	= 10 - 80x25 color	
	= 11 - 80x25 monochrome	
Bit 3	Reserved	
Bit 2	Pointing device	
Bit 1	Math coprocessor	
Bit 0	IPL diskette	
Exceptions:		
Bit 13	Internal modem (for PC Convertible and	
	Personal System/2 Model 55 LS)	
Bit 2	Reserved (for PC, PC/XT, AT, and PC	
	Convertible)	

Figure 3-3. System Equipment Data Area

Address		
(Hex)	Function	Size
40:12	Reserved	Byte
Exceptions:		
40:12	Power-on self-test status (for PC Convertible only)	Byte
	POST system flag (for Personal System/2 Model 25 only)	Byte
Bit 1	Real-time clock (RTC) installed	
Bit 0	Optional memory failed; memory remapped	

Figure 3-4. Miscellaneous Data Area 1

Address (Hex)	Function	Size
40:13	Memory size, in KB (range of 0KB to 640KB)	Word
40:15, 40:16	Reserved	Byte

Figure 3-5. Memory Size Data Area

Address (Hex)	Function	Size
40:17	Keyboard control	Byte
Bit 7	Insert locked	
Bit 6	Caps Lock locked	
Bit 5	Num Lock locked	
Bit 4	Scroll Lock locked	
Bit 3	Alt key pressed	
Bit 2	Ctrl key pressed	
Bit 1	Left Shift key pressed	
Bit 0	Right Shift key pressed	
	/102-key keyboard support, bits 2 and 3 are set if and the Ctrl key are pressed.	either or both the
40:18	Keyboard control	Byte
Bit 7	Insert key pressed	-
Bit 6	Caps Lock key pressed	
Bit 5	Num Lock key pressed	
Bit 4	Scroll Lock key pressed	
Bit 3	Pause locked	
Bit 2	SysRq key pressed	
Bit 1	Left Alt key pressed	
Bit 0	Left Ctrl key pressed	
40:19	Alternate keypad entry	Byte
40:1A	Keyboard buffer head pointer	Word
40:1C	Keyboard buffer tail pointer	Word
40:1E	Keyboard buffer	32 bytes

Figure 3-6. Keyboard Data Area 1

Address		
(Hex)	Function	Size
40:3E	Recalibrate status	Byte
Bit 7	Interrupt flag	•
Bit 6	Reserved	
Bit 5	Reserved	
Bit 4	Reserved	
Bit 3	Recalibrate drive 3	
Bit 2	Recalibrate drive 2	
Bit 1	Recalibrate drive 1	
Bit 0	Recalibrate drive 0	
40:3F	Motor status	Byte
Bit 7	Write/read operation	5,10
Bit 6	Reserved	
Bits 5, 4	Diskette drive select status (values in	
	binary)	
	= 00 - Diskette drive 0 selected	
	= 01 - Diskette drive 1 selected	
	= 10 - Diskette drive 2 selected	
	= 11 - Diskette drive 3 selected	
Bit 3	Diskette drive 3 motor-on status	
Bit 2	Diskette drive 2 motor-on status	
Bit 1	Diskette drive 1 motor-on status	
Bit 0	Diskette drive 0 motor-on status	
	Diskelle drive o motor-on status	
40:40	Motor off counter	Byte
40:41	Last diskette drive operation status	Byte
	= 00H - No error	5,00
	= 01H - Invalid diskette drive parameter	
	= 02H - Address mark not found	
	= 03H - Write-protect error	
	= 04H - Requested sector not found	
	= 06H - Diskette change line active	
	= 08H - DMA overrun on operation	
	= 09H - Attempt to DMA across a 64KB	
[boundary	
	= 0CH - Media type not found	
	= 10H - CRC error on diskette read	
	= 20H - General controller failure	
1	= 30H - Drive does not support media	
	sense	
	= 31H - No media in drive	
	= 32H - Drive does not support media	
	type	
	= 40H - Seek operation failed	
	= 80H - Time-out	
	= AAH - Diskette drive not ready	
L,,	·	

Figure 3-7 (Part 1 of 2). Diskette Drive Data Area

Address (Hex)	Function	Size
40:42	Diskette-drive controller status bytes	7 bytes

Figure 3-7 (Part 2 of 2). Diskette Drive Data Area

Address (Hex)	Function	Size
40:49	Display mode set	Byte
40:4A	Number of columns	Word
40:4C	Length of regen buffer, in bytes	Word
40:4E	Starting address in regen buffer	Word
40:50	Cursor position page 1	Word
40:52	Cursor position page 2	Word
40:54	Cursor position page 3	Word
40:56	Cursor position page 4	Word
40:58	Cursor position page 5	Word
40:5A	Cursor position page 6	Word
40:5C	Cursor position page 7	Word
40:5E	Cursor position page 8	Word
40:60	Cursor type	Word
40:62	Display page	Byte
40:63	Display controller base address	Word
40:65	Current setting of 3x8 register	Byte
40:66	Current setting of 3x9 register	Byte

Figure 3-8. Video-Control Data Area 1

Address (Hex)	Function	Size
40:67	Reserved	DWord
40:6B	Reserved	Byte
Exception: 40:67	Pointer to reset code upon system reset with memory preserved (for Personal System/2 products except Model 25 and Model 30) Reset flag at hex 40:72 = 4321H	DWord

Figure 3-9. System Data Area 1

Address (Hex)	Function	Size
40:6C	Timer counter	DWord
40:70	Timer overflow (If nonzero, the timer has counted past 24 hours.)	Byte

Figure 3-10. System-Timer Data Area

Address (Hex)	Function	Size
40:71	Break key state	Byte
Bit 7	= 1 - Break key pressed	
	= 0 - Break key not pressed	
40:72	Reset flag	Word
	= 1234H - Bypass memory test	
	= 4321H - Preserve memory (for Personal	
	System/2 products except Model 25 and Model 30)	
	= 5678H - System suspended (for	
	PC Convertible)	
	= 9ABCH - Manufacturing test mode	
	(for PC Convertible)	
	= ABCDH - System POST loop mode	
	(for PC Convertible)	

Figure 3-11. System Data Area 2

r ·		
Address	Function	01 <i>m</i> -
(Hex)	Function	Size
40:74	Last fixed disk drive operation status	Byte
	00H = No error	_, _
	01H = Invalid function request	
	02H = Address mark not found	
	03H = Write protect error	
	04H = Sector not found	
	05H = Reset failed	
	07H = Drive parameter activity failed	
	08H = DMA overrun on operation	
	09H = Data boundary error	
	0AH = Bad sector flag detected	
	0BH = Bad track detected	
	0DH = Invalid number of sectors on	
1	format	
	0EH = Control data address mark	
1	detected	
	0FH = DMA arbitration level out of	
	range	
	10H = Uncorrectable ECC or CRC error	
	11H = ECC corrected data error	
	20H = General controller failure	
	40H = Seek operation failed	
	80H = Time-out	
	AAH = Drive not ready	
	BBH = Undefined error occurred	
	CCH = Write fault on selected drive	
	E0H = Status error/error register is 0	
	FFH = Sense operation failed	
40:75	Number of fixed disk drives attached	Byte
		-
40:76	Reserved	Byte
40:77	Reserved	Byte
_		
Exceptions:	• • • • • • • • • • • • • • • • • • •	
40:74	Reserved (for devices using ESDI-type	Byte
	commands)	
40:76	Fixed disk drive control (for PC/XT)	Bute
		Byte
40:77	Fixed disk drive controller port (for PC/XT)	Byte
	. Mee alok arre controller port (lot 1 0/X1)	5,10

Figure 3-12. Fixed Disk Drive Data Area

Address		
(Hex)	Function	Size
40:78	Printer 1 time-out value	Byte
40:79	Printer 2 time-out value	Byte
40:7A	Printer 3 time-out value	Byte
40:7B	Generic SCSI CBIOS and bus-master filter flags	
Bits 7, 6	Reserved	
Bit 5	Operating-system DMA services indicator	
	= 0 - Not supported; all memory is	
	mapped linear = physical	
	= 1 - Supported	
Bit 4	Reserved	
Bit 3	Interrupt-4BH-intercepted indicator	
	= 0 - Interrupt vector is not intercepted	
	= 1 - Interrupt vector is intercepted	
Bit 2	Reserved	
Bit 1	Generic SCSI CBIOS services support	
	= 0 - Interrupt 4BH does not support	
	SCSI	
	= 1 - Interrupt 4BH supports SCSI	
Bit 0	Reserved	
Exception:		
40:7B	Printer 4 time-out value (for PC, PC/XT, AT,	Byte
	and Personal System/2 Model 25 and Model 30)	•
L		

Figure 3-13. Printer Time-Out Value Data Area

Address (Hex)	Function	Size
40:7C	RS-232C communication line 1 time-out value	Byte
40:7D	RS-232C communication line 2 time-out value	Byte
40:7E	RS-232C communication line 3 time-out value	Byte
40:7F	RS-232C communication line 4 time-out value	Byte

Figure 3-14. RS-232C Time-Out Value Data Area

Address (Hex)	Function	Size
40:80	Keyboard buffer start offset pointer	Word
40:82	Keyboard buffer end offset pointer	Word

Figure 3-15. Keyboard Data Area 2

Address (Hex)	Function	Size
40:84	Number of rows on the screen (minus 1)	Byte
40:85	Character height (bytes/character)	Word
40:87	Video control states	Byte
40:88	Video control states	Byte
40:89	Reserved	Byte
40:8A	Reserved	Byte
		0,10

Figure 3-16. Video-Control Data Area 2

Address (Hex)	Function	Size
• •	· · · · · ·	
40:8B	Media control	Byte
Bits 7, 6	Last diskette drive data rate selected	
	(values in binary)	
	= 00 - 500KB per second	
	= 01 - 300KB per second	
	= 10 - 250KB per second = 11 - 1MB per second	
Bits 5, 4	Last diskette drive step rate selected	
5113 0, 4	= 00 - 0CH	
	= 01 - 0DH	
	= 10 - 0EH	
	= 11 - 0AH	
Bit 3	Reserved	
Bit 2	Reserved	
Bit 1	Reserved	
Bit 0	Reserved	
40:8C	Fixed disk drive controller status	Byte
40:8D	Fixed disk drive controller error status	Byte
40:8E	Fixed disk drive interrupt control	Byte
40:8F	Reserved	Byte

Figure 3-17 (Part 1 of 5). Diskette Drive/Fixed Disk Drive Control Data Area

Address (Hex)	Function	Size
40:90 Bits 7, 6	Drive 0 media state Data transfer rate (values in binary) = 00 - 500KB per second = 01 - 300KB per second	Byte
	= 10 - 250KB per second = 11 - 1MB per second	
Bit 5	Double stepping = 1 - Double stepping required	
Bit 4	 = 0 - Double stepping not required Media/drive established = 1 - Media/drive has been established 	
Bit 3	 = 0 - Media/drive has not been established 4MB media capability = 1 - Drive is capable of supporting 4MB 	
	media = 0 - Drive is not capable of supporting 4MB media	
Bits 2 to 0	Drive/media state (values in binary) = 000 - 360KB diskette in 360KB drive is not established	
	= 001 - 360KB diskette in 1.2MB drive is not established	
	= 010 - 1.2MB diskette in 1.2MB drive is not established = 011 - 360KB diskette in 360KB drive is	
	established = 100 - 360KB diskette in 1.2MB drive is established	
	= 101 - 1.2MB diskette in 1.2MB drive is established	
	= 110 - Reserved = 111 - None of the above	

Figure 3-17 (Part 2 of 5). Diskette Drive/Fixed Disk Drive Control Data Area

Addusse		· · · · · · · · · · · · · · · · · · ·
Address		
(Hex)	Function	Size
40:91	Drive 1 media state	Pute
Bits 7, 6	Data transfer rate (values in binary)	Byte
	= 00 - 500KB per second	
	= 01 - 300KB per second	
	= 10 - 250KB per second	
	= 11 - 1MB per second	
Bit 5	Double stepping	
	= 1 - Double stepping required	
	= 0 - Double stepping not required	
Bit 4	Media/drive established	
	= 1 - Media/drive has been established	
	= 0 - Media/drive has not been established	
Bit 3	4MB media capability	
	= 1 - Drive is capable of supporting 4MB	
	media	
	= 0 - Drive is not capable of supporting	
	4MB media	
Bits 2 to 0	Drive/media state (values in binary)	
	= 000 - 360KB diskette in 360KB drive is	
	not established	
	= 001 - 360KB diskette in 1.2MB drive is	
	not established	
	= 010 - 1.2MB diskette in 1.2MB drive is	
	not established	
	= 011 - 360KB diskette in 360KB drive is	
	established	
	= 100 - 360KB diskette in 1.2MB drive is	
	established	
	= 101 - 1.2MB diskette in 1.2MB drive is	
	established	
	= 110 - Reserved	
	= 111 - None of the above	

Figure 3-17 (Part 3 of 5). Diskette Drive/Fixed Disk Drive Control Data Area

(Hex) Function Siz 40:92 Drive 2 media state Byt Bits 7, 6 Data transfer rate (values in binary) = Byt = 00 - 500KB per second = 01 - 300KB per second = 10 - 250KB per second = 10 - 250KB per second = 11 - 1MB per second = 11 - 1MB per second Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	9
Bits 7, 6 Data transfer rate (values in binary) = 00 - 500KB per second = 01 - 300KB per second = 10 - 250KB per second = 11 - 1MB per second Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	
= 00 - 500KB per second = 01 - 300KB per second = 10 - 250KB per second = 11 - 1MB per second Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	e
= 01 - 300KB per second = 10 - 250KB per second = 11 - 1MB per second Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	
= 10 - 250KB per second = 11 - 1MB per second Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	
= 11 - 1MB per second Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	
Bit 5 Double stepping = 1 - Double stepping required = 0 - Double stepping not required	
= 1 - Double stepping required = 0 - Double stepping not required	
= 0 - Double stepping not required	
Bit 4 Media/drive established	
= 1 - Media/drive has been established	
= 0 - Media/drive has not been established	
Bit 3 4MB media capability	
= 1 - Drive is capable of supporting 4MB media	
= 0 - Drive is not capable of supporting 4MB media	
Bit 2 Multiple data rate capability determined	
= 1 - Multiple data rate capability is	
determined	
= 0 - Multiple data rate capability is not determined	
Bit 1 Multiple data rate capability	
= 1 - Multiple data rate capability	
= 0 - No multiple data rate capability	
Bit 0 80-track capability (drive 2)	
= 1 - Drive 2, 80 tracks	
= 0 - Drive 2, 40 tracks	

Figure 3-17 (Part 4 of 5). Diskette Drive/Fixed Disk Drive Control Data Area

Address		
(Hex)	Function	Size
40:93	Drive 3 media state	Byte
Bits 7, 6	Data transfer rate (values in binary)	
	= 00 - 500KB per second	
	= 01 - 300KB per second	
	= 10 - 250KB per second	
	= 11 - 1MB per second	
Bit 5	Double stepping	
	= 1 - Double stepping required	
	= 0 - Double stepping not required	
Bit 4	Media/drive established	
	= 1 - Media/drive has been established	
	= 0 - Media/drive has not been established	
Bit 3	4MB media capability	
	 = 1 - Drive is capable of supporting 4MB media 	
	= 0 - Drive is not capable of supporting 4MB media	
Bit 2	Multiple data rate capability determined	
z	 = 1 - Multiple data rate capability is determined 	
	= 0 - Multiple data rate capability is not determined	
Bit 1	Multiple data rate capability	
	= 1 - Multiple data rate capability	
	= 0 - No multiple data rate capability	
Bit 0	80-track capability (drive 3)	
	= 1 - Drive 3, 80 tracks	
	= 0 - Drive 3, 40 tracks	
40:94	Drive 0 current cylinder	Byte
40:95	Drive 1 current cylinder	Byte
Exception:		
40:8B to 40:95	Reserved (for PC, PC <i>jr</i> , PC/XT BIOS dated 11/8/82, and PC Convertible)	Byte

Figure 3-17 (Part 5 of 5). Diskette Drive/Fixed Disk Drive Control Data Area

Address (Hex)	Function	Size
40:96	Keyboard mode state and type flags	Byte
Bit 7	Read ID in progress	•
Bit 6	Last character was first ID character	
Bit 5	Force num lock if read ID and KBX	
Bit 4	101/102-key keyboard installed	
Bit 3	Right Alt key pressed	
Bit 2	Right Ctrl key pressed	
Bit 1	Last code was E0 hidden code	
Bit 0	Last code was E1 hidden code	
40:97	Keyboard LED flags	Byte
Bit 7	Keyboard transmit error flag	•
Bit 6	Mode indicator update	
Bit 5	Resend receive flag	
Bit 4	Acknowledgment received	
Bit 3	Reserved (must be set to 0)	
Bits 2 to 0	Keyboard LED state bits	

Figure 3-18. Keyboard Data Area 3

Address (Hex)	Function	Size
40:98	Offset address to user wait complete flag	Word
40:9A	Segment address to user wait complete flag	Word
40:9C	User wait count - low word (in microseconds)	Word
40:9E	User wait count - high word (in microseconds)	Word
40:A0 Bit 7 Bits 6 to 1 Bit 0	Wait active flag Wait time elapsed and Post Reserved Interrupt 15H, Weit function ((AH) = 85H)	Byte
ыю	Interrupt 15H, Wait function ((AH) = 86H) has occurred	
40:A1 to 40:A7	Reserved	Byte

Figure 3-19. Real-Time Clock Data Area

For Personal System/2 products and systems with EGA capability, the save pointer table contains pointers that define specific dynamic overrides for Interrupt 10H, Set Mode function ((AH) = 00H).

Address (Hex)	Function	Size
10.40	- · · · · · ·	
40:A8	Pointer to video parameters and overrides	DWord
DWord 1	Video parameter table pointer	
	Initialized to the BIOS video parameter	
	table; this value must contain a valid pointer.	
DWord 2	Dynamic save area pointer (for all systems	
	except Personal System/2 Model 25 and Model 30)	
	Initialized to hex 00:00, this value is	
	optional. When nonzero, this value	
	points to an area in RAM where certain	
	dynamic values are saved. This area	
	holds the 16 EGA palette register	
	values plus the overscan value in	
	bytes (0 16), respectively. A	
	minimum of 256 bytes must be	
	allocated for this area.	
DWord 3	Alphanumeric mode auxiliary character	
	generator	
	Initialized to hex 00:00, this value is	
	optional. When nonzero, this value	
	points to a table that is described as	
	follows:	
	Bytes/character	Byte
	Block to be loaded	Byte
	= 0 - Normal operation	
	Count to be stored	Word
	= 256 - Normal operation	
	Character offset	Word
	= 0 - Normal operation	
	Pointer to a font table	DWord
	Displayable rows	Byte
	If 0FFH, the maximum calculated value	-
	is used. Otherwise, this value is used.	
	Consecutive bytes of mode values for	Byte
	this font description. The end of	
	this stream is indicated by a byte	
	code of 0FFH.	
Note: Use of the D For an expla function ((Al	Word 3 pointer might cause unexpected cursor type mation of cursor type, see Interrupt 10H, Set Cursor	operation. Type

Figure 3-20 (Part 1 of 2). Save Pointer Data Area

Address (Hex)	Function	Size
DWord 4	Graphics mode auxiliary character	
	generator pointer	
	Initialized to hex 00:00, this value is	
	optional. When nonzero, this value	
	points to a table that is described as follows:	
	Displayable rows	Byte
	Bytes per character	Word
	Pointer to a font table	DWord
	Consecutive bytes of mode values for	Byte
	this font description. The end of	2,.0
	this stream is indicated by a byte code of 0FFH.	
DWord 5	Secondary save pointer (for all systems	
	except EGA and Personal System/2	
	Model 25 and Model 30)	
	Initialized to the BIOS secondary save	
	pointer; this value must contain a valid	
	pointer.	
DWord 6	Reserved and set to hex 00:00	
DWord 7	Reserved and set to hex 00:00	

Figure 3-20 (Part 2 of 2). Save Pointer Data Area

Address (Hex)	Function	Size
DWord 1	Table length	
	initialized to the BIOS secondary save	
	pointer table length	
DWord 2	Display combination code (DCC) table pointer	
	initialized to ROM DCC table. This value	
	must exist. It points to a table described	
	as follows:	
	Number of entries in table	Byte
	DCC table version number	Byte
	Maximum display type code	Byte
	Reserved	Byte
	00,00 - Entry 0 No displays	
	00,01 - Entry 1 Monochrome display	
	and printer adapter (MDPA)	
	00,02 - Entry 2 Color/graphics monitor	
	adapter (CGA)	
	02,01 - Entry 3 MDPA + CGA	
	00,04 - Entry 4 Enhanced graphics	
	adapter (EGA)	
	04,01 - Entry 5 EGA + MDPA	
	00,05 - Entry 6 EGA with monochrome	
	display (MEGA) 02,05 - Entry 7 MEGA + CGA	
	00,06 - Entry 8 Professional graphics	
	controller (PGC)	
	01,06 - Entry 9 PGC + MDPA	
	05,06 - Entry 10 PGC + MEGA	
	00,08 - Entry 11 Video graphics array	
	(VGA) based with color display (CVGA)	
	01,08 - Entry 12 CVGA + MDPA	
	00,07 - Entry 13 VGA based with	
	monochrome display (MVGA)	
	02,07 - Entry 14 MVGA + CGA	
	02,06 - Entry 15 MVGA + PGC	
	•	

Figure 3-21 (Part 1 of 2). Secondary Save Pointer Data Area

Address Hex)	Function	Size
DWord 3	Second alphanumeric mode auxiliary	
Divold 0	character generator pointer	
	Initialized to hex 00:00, this value is	
	optional. When nonzero, this value	
	points to a table that is described as	
	follows:	
	Bytes/character	Dida
	Block to be loaded	Byte
		Byte
	= 0 - Normal operation Reserved	D. A.
	Pointer to a font table	Byte
		DWord
	Consecutive bytes of mode values for	Byte
	this font description. The end of	
	this stream is indicated by a byte	
	code of 0FFH.	.
	bit 3 is used to switch between primary and secondar	
	tesirable to use the user palette profile to define a pa	alette of
	colors independent of attribute bit 3.	
DWord 4	User palette profile table pointer	
	Initialized to hex 00:00, this value is	
	optional. When nonzero, this value	
	points to a table that is described as	
	follows:	
	Underlining flag	Byte
	= 1 - On	
	= 0 - Ignore	
	= -1 - Off	
	= 0 - Normal operation	
	Reserved	Byte
	Reserved	Word
	Internal palette count (0 to 17)	Word
	= 17 - Normal operation	
	Internal palette index (0 to 16)	Word
	= 0 - Normal operation	
	Pointer to internal palette	DWord
	External palette count (0 to 256)	Word
	= 256 - Normal operation	
	External palette index (0 to 255)	Word
	= 0 - Normal operation	
	Pointer to external palette	DWord
	Consecutive bytes of mode values for	Byte
	this font description. The end of	•
	this stream is indicated by a byte	
	code of 0FFH.	
DWord 5 to	Reserved (set to hex 00:00)	

Figure 3-21 (Part 2 of 2). Secondary Save Pointer Data Area

Address (Hex)	Function	Size
40:AC to 40:FF	Reserved	Byte
50:00	Print screen status (Interrupt 05H status)	Byte

Figure 3-22. Miscellaneous Data Area 2

Extended BIOS Data Areas

The extended BIOS data area is supported on Personal System/2 products only. POST allocates the highest possible nKB of memory below 640KB to be used as this data area. The word value at address hex 40:13 (memory size), which indicates the number of KB below the 640KB limit, is decreased by n. The first byte in the extended BIOS data area is initialized to the length of the allocated area, in KB.

To access the extended BIOS data area segment, call Interrupt 15H, Return Extended BIOS Data Area Segment Address function ((AH) = C1H). To determine whether an extended BIOS data area is allocated, call Interrupt 15H, Return System Configuration Parameters function ((AH) = C0H).

Section 4. ROM Tables

The following ROM tables are used by BIOS to define the characteristics of the hardware devices that are supported by the system or adapter BIOS.

Fixed Disk Drive Parameter Table

The fixed disk drive parameter table is defined as follows:

0 Word Maximum number of cylinders 2 Byte Maximum number of heads 3 Word For PC/XT: Starting reduced write current cylinder 5 Word Starting write precompensation cylinder 7 Byte For PC/XT: Maximum ECC data-burst length 8 Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option Bits 2 to 0 - Drive option	r :
3 Word For PC/XT: Starting reduced write current cylinder 5 Word Starting write precompensation cylinder 7 Byte For PC/XT: Maximum ECC data-burst length 8 Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 5 to 3 = 0 Bits 2 to 0 - Drive option	r
For all others: Not used 5 Word Starting write precompensation cylinder 7 Byte For PC/XT: Maximum ECC data-burst length For all others: Not used 8 Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	r
For all others: Not used Word Starting write precompensation cylinder For PC/XT: Maximum ECC data-burst length For all others: Not used B Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	
7 Byte For PC/XT: Maximum ECC data-burst length For all others: Not used 8 Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	
For all others: Not used B Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	
For all others: Not used B Byte Control byte For PC/XT: Bit 7 - Disable disk-access retries Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	
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Bit 6 - Disable ECC retries Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	
Bits 5 to 3 = 0 Bits 2 to 0 - Drive option	
Bits 2 to 0 - Drive option	
For all others:	
Bit 7 - Disable retries	
- or -	
Bit 6 - Disable retries	
Bit 5 - Manufacturer's defect map present at	
maximum cylinders + 1	
Bit 3 - More than eight heads	
Bits 2 to 0 - Reserved	
9 Byte For PC/XT: Standard time-out value	
For all others: Not used	
10 Byte For PC/XT: Time-out value for format drive	
For all others: Not used	
11 Byte For PC/XT: Time-out value for check drive	
For all others: Not used	
12 Word For PC/XT: Reserved	
For all others: Landing zone	
14 Byte For PC/XT: Reserved	
For all others: Number of sectors per track	
15 Byte Reserved	

Figure 4-1. Fixed Disk Drive Parameter Table

For AT and Personal System/2 products, the following table lists the fixed disk drive parameters for the various fixed disk drive types. Values are decimal unless noted otherwise.

	of	of	Number Write	Landing	Defect	Numbe of
Туре	Cylinders	Heads	Precompensation	Zone	Мар	Sectors
0	- No fixed	disk drive	installed -			
1	306	4	128	305	No	17
2	615	4	300	615	No	17
3	615	6	300	615	No	17
4	940	8	512	940	No	17
5	940	6	512	940	No	17
6	615	4	0FFFFH (None)	615	No	17
7	462	8	256	511	No	17
8	733	5	0FFFFH (None)	733	No	17
9	900	15	0FFFFH (None)	901	No	17
10	820	3	0FFFFH (None)	820	No	17
11	855	5	0FFFFH (None)	855	No	17
12	855	7	0FFFFH (None)	855	No	17
13	306	8	128	319	No	17
14	733	7	0FFFFH (None)	733	No	17
15	- Reserve	-		100	110	.,
16	612	4	0 (All cylinders)	663	No	17
17	977	5	300	977	No	17
18	977	7	0FFFFH (None)	977	No	17
19	1024	7	512	1023	No	17
20	733	5	300	732	No	17
21	733	7	300	732	No	17
22	733	5	300	733	No	17
23	306	4	0 (All cylinders)	336	No	17
23	612	4	305	663	No	17
25	306	4	OFFFFH (None)	340	No	17
25	506 612	4	OFFFFH (None)	340 670	No	17
20	698	4 7	300	732	Yes	17
27	976	5	488	732 977		17
28 29		5 4			Yes	
	306	4	0 (All cylinders)	340	No	17
30	611		306	663	Yes	17
31	732	7	300	732	Yes	17
32	1023	5	0FFFFH (None)	1023	Yes	17
33	614	4	0FFFFH (None)	663	Yes	25

Figure 4-2. Fixed Disk Drive Parameters (for AT and Personal System/2 Products)

Notes:

- 1. Software Interrupt 41H points to the entry in the table for drive 0. Software Interrupt 46H points to the entry in the table for drive 1.
- 2. AT BIOS dated 1/10/84 supports types 0 through 14.
- 3. AT BIOS dated 6/10/85 or 11/15/85 supports types 0 through 23.
- 4. PC/XT Model 286 supports types 0 through 24.
- 5. Personal System/2 products except Model 25 and Model 30 support types 0 through 32.
- 6. Personal System/2 Model 30 supports types 0 through 26.
- 7. For Personal System/2 Model 70 and Model 80 BIOS dated 10/7/87 and later and self-identifying drives, the fixed disk drive parameters in Figure 4-2 on page 4-2 and Figure 4-3 do not apply; software Interrupts 41H and 46H are reserved.
- 8. To obtain the fixed disk drive parameters, use Interrupt 13H, Read Drive Parameters function ((AH) = 08H).

Offset	Length	Value	Description
0	2 bytes	41	Length of fixed disk drive table
2	22 bytes	(ID)	ASCII string 'IBM HARDFILE TYPE xxx', where xxx is the type number, in ASCII
24	1 byte	ууу	Type number (in binary)
25	2 bytes	*	Maximum number of cylinders
27	1 byte	*	Maximum number of heads
28	2 bytes	0	Reserved
30	2 bytes	*	Start write precompensation cylinder
32	1 byte	0	Reserved
33	1 byte	*	Control byte
			Bit 7 or 6 - Disable retries
			Bit 5 - Defect map installed
			Bit 3 - More than eight heads (AT only)
34	3 bytes	0	Reserved
37	2 bytes	•	Landing zone
39	1 byte	*	Number of sectors per track
40	1 byte	0	Reserved

For Personal System/2 products except Model 25 and Model 30, the following fixed disk drive parameters apply:

Figure 4-3. Fixed Disk Drive Parameters (for Personal System/2 Products except Model 25 and Model 30) For PC/XT BIOS dated 11/10/82, the following fixed disk drive parameters apply:

Size	Value	Description
DW	306	Maximum cylinders
DB	2	Maximum heads
DW	306	Start reduced write current cylinder
DW	0	Start write precompensation cylinder
DB	08H	Maximum ECC burst data length
DB	00H	Control byte
DB	0CH	Standard time-out
DB	0B4H	Time-out for format drive
DB	028H	Time-out for check drive
DB	0,0,0,0	Reserved

Figure 4-4. Fixed Disk Drive Parameter Table 00 (for PC/XT BIOS Dated 11/10/82)

Size	Value	Description	
DW	375	Maximum cylinders	
DB	8	Maximum heads	
DW	375	Start reduced write current cylinder	
ÐW	0	Start write precompensation cylinder	
DB	0BH	Maximum ECC burst data length	
DB	05H	Control byte	
DB	0CH	Standard time-out	
DB	0B4H	Time-out for format drive	
DB	028H	Time-out for check drive	
DB	0.0.0.0	Reserved	

Figure 4-5. Fixed Disk Drive Parameter Table 01 (for PC/XT BIOS Dated 11/10/82)

Size	Value	Description	
DW	306	Maximum cylinders	
DB	6	Maximum heads	
DW	128	Start reduced write current cylinder	
DW	256	Start write precompensation cylinder	
DB	0BH	Maximum ECC burst data length	
DB	05H	Control byte	
DB	0CH	Standard time-out	
DB	0B4H	Time-out for format drive	
DB	028H	Time-out for check drive	
DB	0,0,0,0	Reserved	

Figure 4-6. Fixed Disk Drive Parameter Table 02 (for PC/XT BIOS Dated 11/10/82)

Size	Value	Description	
DW	306	Maximum cylinders	
DB	4	Maximum heads	
DW	306	Start reduced write current cylinder	
DW	0	Start write precompensation cylinder	
DB	0BH	Maximum ECC burst data length	
DB	05H	Control byte	
DB	0CH	Standard time-out	
DB	0B4H	Time-out for format drive	
DB	028H	Time-out for check drive	
DB	0.0,0,0	Reserved	

Figure 4-7. Fixed Disk Drive Parameter Table 03 (for PC/XT BIOS Dated 11/10/82)

Note: Software Interrupt 41H points to the beginning of the table. The switch settings on the adapter are used as an index into the table. For PC/XT BIOS dated 1/8/86 and later, the following fixed disk drive parameters apply:

Size	Value	Description			
DW	306	Maximum cylinders			
DB	4	Maximum heads			
DW	306	Start reduced write current cylinder			
DW	0	Start write precompensation cylinder			
DB	0BH	Maximum ECC burst data length			
DB	05H	Control byte			
DB	0CH	Standard time-out			
DB	0B4H	Time-out for format drive			
DB	028H	Time-out for check drive			
DB	0,0,0,0	Reserved			

Figure 4-8. Fixed Disk Drive Parameter Table 00 – Type 1 (for PC/XT BIOS Dated 1/8/86)

Size	Value	Description			
DW	612	Maximum cylinders			
DB	4	Maximum heads			
DW	612	Start reduced write current cylinder			
DW	0	Start write precompensation cylinder			
DB	0BH	Maximum ECC burst data length			
DB	05H	Control byte			
DB	20H	Standard time-out			
DB	0B4H	Time-out for format drive			
DB	028H	Time-out for check drive			
DB	0,0,0,0	Reserved			

Figure 4-9. Fixed Disk Drive Parameter Table 01 – Type 16 (for PC/XT BIOS Dated 1/8/86)

Size	ize Value Description					
DW	615	Maximum cylinders				
DB	4	Maximum heads				
DW	615	Start reduced write current cylinder				
DW	300	Start write precompensation cylinder				
DB	0BH	Maximum ECC burst data length				
DB	05H	Control byte				
DB	18H	Standard time-out				
DB	0B4H	Time-out for format drive				
DB	028H	Time-out for check drive				
DB	0,0,0,0	Reserved				

Figure 4-10. Fixed Disk Drive Parameter Table 02 – Type 2 (for PC/XT BIOS Dated 1/8/86)

Size	Value	Description			
DW	306	Maximum cylinders			
DB	8	Maximum heads			
DW	306	Start reduced write current cylinder			
DW	128	Start write precompensation cylinder			
DB	0BH	Maximum ECC burst data length			
DB	05H	Control byte			
DB	0CH	Standard time-out			
DB	0B4H	Time-out for format drive			
DB	028H	Time-out for check drive			
DB	0,0,0,0	Reserved			

Figure 4-11. Fixed Disk Drive Parameter Table 03 – Type 13 (for PC/XT BIOS Dated 1/8/86)

Note: Software Interrupt 41H points to the beginning of the table. The switch settings on the adapter are used as an index into the table.

Diskette Drive Parameter Table

The diskette drive parameter table is defined as follows:

Offset	Length	Description			
o	Byte	First specification byte			
1	Byte	Second specification byte			
2	Byte	Number of timer ticks to wait before turning the diskette drive motor off			
3	Byte	Number of bytes per sector = 02H - 512 bytes per sector			
4	Byte	Sectors per track			
5	Byte	Gap length			
6	Byte	Dtl (data length)			
7	Byte	Gap length for format			
8	Byte	Fill byte for format			
9	Byte	Head settle time (in milliseconds)			
10	Byte	Motor startup time (in ½-second units) (For example, 8=1-second wait)			

Figure 4-12. Diskette Drive Parameter Table

Note: Software Interrupt 1EH points to the beginning of the diskette drive parameter table.

If the caller changes the values of the head settle time (byte 9) and the motor startup time (byte 10) to values that are inconsistent with the diskette drive specifications, BIOS enforces the minimum values for these parameters as specified for the diskette drive. The values of these parameters can be increased to allow for correcting possible future problems if some diskette drives require more than the nominal values for these parameters.

Section 5. Additional Information

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Notes:

Interrupt Sharing

This section defines an interrupt-sharing protocol that enables multiple hardware adapters to share a single interrupt-request line.

Considerations

When implementing interrupt sharing, consider the following:

- The interrupt-sharing protocol is intended to run only in the real address mode. It is not intended to run in the protected (virtual address) mode.
- The interrupt-sharing protocol does not apply to the sharing of an interrupt level between an interrupt handler that is running in the real mode and an interrupt handler that is running in the protected mode.
- The interrupt-sharing protocol is not necessarily compatible with all operating systems.
- Interrupts must be disabled before control is passed to the next handler on the chain. Disabling of the interrupts enables the next handler to receive control as if a hardware interrupt had caused it to receive control.
- Interrupts must be disabled before the nonspecific End of Interrupt (EOI) instruction is issued. To ensure that the Return from Interrupt (IRET) instruction is executed, interrupts must not be reenabled in the interrupt handler. The flags are restored and the interrupts are reenabled before another interrupt is serviced, protecting the stack from excessive build-up.
- Each interrupt handler must have a routine that can be executed after power-on to disable its adapters' interrupts. Executing this routine and resetting the interrupt-sharing hardware ensures that adapters are deactivated if the user resets the system.
- Interrupt-handler implementations must store data in memory using Intel^{**} data format; that is, word hex 424B is stored as 4BH,42H in memory.

^{**} Intel is a trademark of Intel Corporation.

Interrupt Request (IRQ n) Reset

The Micro Channel interrupt mechanism is level sensitive, whereas the PC-type I/O channel interrupt mechanism is edge sensitive. The level-sensitive Micro Channel mechanism simplifies the interrupt hardware that is needed for the adapters.

An interrupt request in the PC-type I/O channel is implicitly reset because of the edge-sensitive characteristic of the signal. In the Micro Channel architecture, because of the level-sensitive characteristic of the signal, an interrupt request must be explicitly reset by the bus-slave interrupt-handler software. This is not the case when the bus-slave hardware implicitly resets the interrupt request. The system timer is an example of a bus-slave device that implicitly resets an interrupt.

Interrupt-Sharing Software Requirements

All interrupt-sharing software that is developed for Micro Channel bus slaves must reset the interrupt request. The interrupt-sharing chaining structure must be provided by all interrupt handlers. The 16-byte interrupt-sharing chaining structure must begin at the third byte from the entry point of the interrupt handler. Pointers and flags that are stored in the interrupt-sharing chaining structure must be stored in Intel data format (see "Interrupt-Sharing Chaining Structure and Signature" on page 5-6). These requirements are specified to support the portability of interrupt handlers across hardware operating environments.

The interrupt-handling software for all adapters that share an interrupt-request line must implement this interrupt-sharing software standard. Interrupt-sharing software that operates in a multitasking environment must support the linking of a task's interrupt handler to a chain of interrupt handlers; the sharing of the interrupt level while that task is active; and the unlinking of the interrupt handler from the chain when the task is complete.

To link an interrupt handler, the interrupt handler of a newly-activated task replaces the interrupt vector in low memory with a pointer to the interrupt handler. (See "ROM Considerations" on page 5-7 for information about interrupt handlers that are stored in ROM.) The interrupt handler must preserve the interrupt vector that it is replacing and use it as a forward pointer to the next interrupt handler in the chain. The old interrupt vector must be stored at a fixed offset from the entry point of the new task's interrupt handler.

When the system acknowledges an interrupt request, each interrupt handler must determine whether it is the appropriate interrupt handler for the adapter that is presenting the interrupt request. To make this determination, the interrupt handler reads the contents of the interrupt-status register of the adapter.

When an interrupt handler determines that its device caused the interrupt, the interrupt handler must service the interrupt, reset the interrupt-status bit, clear the interrupts, issue a nonspecific EOI instruction to the interrupt controller, then execute an IRET instruction.

When an interrupt handler determines that its device did not cause the interrupt, the interrupt handler passes control to the next interrupt handler in the chain, using the previously-stored forward pointer.

To unlink an interrupt handler from a chain, a task first locates the position of its interrupt handler in the chain. The task searches the chain, starting at the interrupt vector in low memory, and using the offset of each interrupt handler's forward pointer to locate the entry point of each interrupt handler. The task repeats this process until it finds its own interrupt handler. The signature (hex 424B) of each interrupt handler must be checked to ensure that a valid forward pointer exists. The forward pointer of the task replaces the forward pointer of the previous interrupt handler in the chain, thus removing the interrupt handler from the chain.

Note: If the interrupt handler cannot locate its position in the chain, the interrupt handler cannot be unlinked.

An application-dependent unlinking error-recovery procedure must be incorporated into the unlinking routine for situations in which the unlinking routine determines that the interrupt chain contains an interrupt handler that is linked but does not have a valid signature. To avoid this error condition, all interrupt-sharing handlers, except those in ROM (see "ROM Considerations" on page 5-7), must use hex 424B as their signature.

In a system-reset condition, a routine for each interrupt handler must be executed after power-on to disable the interrupts from their devices.

Operating-system environments that support dynamic relocation of software must manage the entire interrupt-sharing process. Interrupt-handler software that is written exclusively for dynamic-relocation operating-system environments does not have to provide an interrupt-sharing chaining structure. These interrupt handlers do not have to provide linking and unlinking support, but they must provide support for disabling the interrupt capability of the bus slave that they support.

Interrupt-Sharing Chaining Structure and Signature

The interrupt-sharing software chaining structure has a 16-byte format that contains a 4-byte forward pointer (FPTR), a 2-byte signature, and 8 reserved bytes (RES_BYTES), as shown in the following example:

ENTRY:	JMP	SHORT	PAST	; Jump around structure
	FPTR	DD	0	; Forward pointer
	SIGNATURE	DW	424BH	; Used when unlinking to identify
	FLAGS	DB	0	; compatible interrupt handlers
	FIRST	EQU	80H	; Flags
	JMP	SHORT	RESET	; Flag for being first in chain
PAST:	RES_BYTES	DB	DUP 7(0)	; -Reserved- ; Actual start of code

The interrupt-sharing software chaining structure begins at the third byte from the entry point of the interrupt handler. The first instruction of each interrupt handler is a short jump around the structure, placing the structure at a known offset from the beginning of the interrupt-handler routine. Because the position of the chaining structure of each interrupt handler is known (except for the interrupt handlers on adapter ROM), the forward pointers can be updated during linking and unlinking.

The FIRST flag is used to determine the position of the interrupt handler in the chain during linking and unlinking for shared interrupt levels. The value of the FLAGS byte is changed to the value of the FIRST flag (hex 80) to indicate that the interrupt handler is the first interrupt handler that is linked in the chain. Each interrupt handler that is not stored in ROM must store the FIRST flag (hex 80) in the FLAGS byte when it is the first interrupt handler in the chain.

The Reset routine, an entry point for the operating system, must disable the adapter interrupt and return to the operating system.

ROM Considerations

An adapter with an interrupt handler in ROM must implement chaining by storing the forward pointer in a latch or in a port on the adapter. If the adapter is sharing interrupt level 7 or 15, it must also store the FIRST flag, which indicates whether it is positioned first in the chain of interrupt handlers. Storage of this information is required because it cannot be guaranteed that interrupt handlers in ROM will always link first and never unlink. The forward pointer in ROM interrupt handlers is not stored at the third byte from the entry point of the interrupt handler; therefore the ROM interrupt handler must contain the signature, 0000H, beginning at the seventh byte from the entry point of the interrupt handler.

Implementation Information

The Interrupt Mask register is located at I/O port hex 21. Specific End of Interrupt (EOI) values for the various interrupt levels are listed (hex 67 for level 7). To execute a specific EOI, issue an OUT instruction to the Programmable Interrupt Controller Operation Command register (port hex 20), using operation-command byte 2. To execute a nonspecific EOI, issue an OUT value of hex 20 to the Programmable Interrupt Controller Operation Command register (port hex 20).

The following are examples of code that implements interrupt sharing:

Linking

PUSH ES CLI ;Clear interrupts ;Set forward pointer to value of interrupt vector in low memory ASSUME CS:CODESEG, DS:CODESEG PUSH ES MOV AX,350FH ;DOS get interrupt vector INT 21H SI,OFFSET CS:FPTR ;Get offset of your forward pointer MOV ; in an indexable register MOV CS:[SI].BX ;Store the old interrupt vector MOV CS:[SI+2],ES ; in your forward pointer for ; chaining ES:BYTE PTR[BX], OCFH ;Test for IRET CMP if iret_test_only_is_needed ; See NOTE below JNE SETVECTR else JE FRSTVCTR CMP ES:WORD PTR[BX+6],424BH ; Is signature present? JE SETVECTR MOV AX,ES

CMP AX.0F000H ;See if pointing to dummy handler JNE SETVCTR CMP BX,WORD PTR ES: [OFF01H] ; Dummy vector pointer? :If dummy, then first JNE SETVECTR FRSTVCTR: endif MOV CS:FLAGS.FIRST :Set up first in chain flag SETVECTR: POP ES PUSH DS ;Make interrupt vector in low memory point to your handler MOV DX.OFFSET ENTRY ;Make interrupt vector point to ; your handler MOV AX,SEG ENTRY ; If DS \neq CS, get it and MOV DS,AX ; put it in DS MOV AX,250FH ;DOS set interrupt vector INT 21H POP DS ;Unmask (enable) interrupts for your level IN AL,IMR ;Read interrupt mask register JMP \$+2 :I/O delay AND AL.07FH ;Unmask interrupt level 7 OUT IMR,AL ;Write new interrupt mask MOV AL,SPC EOI ;Issue specific EOI for level 7 JMP \$+2 ; to allow pending level 7 interrupts OUT OCR.AL ; (if any) to be serviced STI ;Enable interrupts POP ES

Notes:

- 1. The operating system must ensure that SEG:OFF points to a valid interrupt handler or to an IRET (hex 0CF) for levels 7 and 15.
- 2. Each ROM interrupt handler during ROMSCAN (before the operating system is loaded) and each interrupt handler on other than IRQ 7 must test SEG:OFF as shown in the "else" clause in this listing to determine whether it is the first interrupt handler in the chain. Checking SEG:OFF to determine whether it points to an IRET as the sole determination of FIRST is allowed only on IRQ 7, and then only after the operating system is loaded.

Interrupt Handler

YOUR_CARD	EQU	xxxx	;Location of your card interrupt ; control/status register
ISB	EQU	XX	;Interrupt bit in your card ; interrupt control/status register
REARM	EQU	2F7H	;Global Rearm location for ; interrupt level 7
SPC_EOI	EQU	67H	:Specific EOI for programmable ; interrupt controller interrupt level 7
EOI	EQU	20H	Nonspecific EOI
OCR	EQU	20H	;Location of programmable interrupt ; controller operation command register

IMR	EQU	21H	;Location of programmable interrupt ; controller interrupt mask
MYCSEG	SEGMENT ASSUME	PARA CS:MYCSEG.DS:DSEG	, controller interrupt mask
ENTRY	PROC	FAR	Fature and the of the disc
FDTD	JMP	SHORT PAST	;Entry point of handler
FPTR	DD DW	0 424BH	;Forward pointer
SIGNATURE	DW	424BH	;Used when unlinking to identify
FLAGS	DB	0	; compatible interrupt handlers ;Flags
FIRST	EOU	80H	Flays
JMP	SHORT	RÉSET	
RES BYTES	DB	7 DUP (0)	:Future expansion
PAST:	STI	7 DOP (0)	;Actual start of handler code
PAST:	PUSH		:Save needed registers
	MOV	DX,YOUR CARD	;Select your status register
	IN	AL.DX	;Read the status register
	TEST	AL,ISB	;Your card caused interrupt?
	JNZ	SERVICE	;Yes, branch to service logic
	TEST	CS:FLAGS,FIRST	Are we the first ones in?
	JNZ	EXIT	; If yes, branch for EOI and Rearm
	POP		Restore registers
	CLI	•••	Clear interrupts
	JMP		:Pass control to next handler on chain
SERVICE:			;Service the interrupt
EXIT:			joervice the interrupt
	CLI		;Clear interrupts
	MOV	AL,EOI	
	OUT	OCR,AL	;Issue nonspecific EOI to programmable
			; interrupt controller
	MOV	DX, REARM	;Rearm the cards
	OUT	DX,AL	
	POP	•••	;Restore registers
	IRET		
RESET:	•••		;Disable your card
	RET		;Return FAR to operating system
ENTRY	ENDP		
MYCSEG	ENDS		
	END	ENTRY	

Unlinking

	ISH DS		
CL			:Clear interrupts
MO	-		:DOS get interrupt vector
IN		• • • • •	ES:BX points to first of chain
MO	V CX		;Pick up segment part of interrupt vector
;Are we the f	irst handl	er in the chain?	
MO	V AX	,CS	;Get code seg into comparable register
CM	IP BX	,OFFSET ENTRY	;Interrupt vector in low memory
			; pointing to your handler offset?
JN	IE UN	CHAIN_A	;No, branch
CM	IP AX	,CX	;Vector pointing to your handler
			; segment?
JN	IE UN	CHAIN_A	;No, branch

		r in low memory to	point to the handler pointed to
; by your p	PUSH	DS	
	MOV		
		DX, WORD PTR CS: FPT	
	MOV	DS, WORD PTR CS: FPT	
	MOV	AX,250FH	;DOS set interrupt vector
	INT	21H	
	POP	DS	
	JMP	UNCHAIN_X	
UNCHAIN_A:			FPTR segment, $CX = CS$
	CMP	ES:[BX+6],4B42H	;Is handler using the appropriate
			; conventions (is SIGNATURE present in
			; the interrupt chaining structure)?
	JNE	exception	;No, invoke error exception handler
	LDS	SI,ES:[BX+2]	;Get FPTR segment and offset
	CMP	SI, OFFSET ENTRY	; Is this forward pointer pointing to
			; your handler offset?
	JNE	UNCHAIN B	:No, branch
	MOV	CX,DS -	;Move to compare
	CMP	AX.CX	;Is this forward pointer pointing to
		·	; your handler segment?
	JNE	UNCHAIN B	:No. branch
:Locate vou	ur handler	in the chain	
	MOV		R ; Get your FPTR offset
	MOV	ES: [BX+2].AX	;Replace offset of FPTR of handler
			; that points to you
	MOV	AX.WORD PTR CS:FTF	PR[2]; Get your FPTR segment
	MOV	ES:[BX+4].AX	;Replace segment of FPTR of handler
			; that points to you
	MOV	AL,CS:FLAGS	;Get your flags
	AND	AL,FIRST	:Isolate FIRST flag
	OR	ES:[BX+6],AL	;Set your first flag into prior routine
	JMP	UNCHAIN X	, see your thist hag into prior routine
UNCHAIN B:		BX.SI	:Move new offset to BX
UNCHAIN_D.	PUSH	DS	;Set pointer to next in chain
	POP	ES	;set pointer to next in chain
	JMP		· Evening next bandles in sheir
		UNCHAIN_A	;Examine next handler in chain
UNCHAIN_X:		FC	;Enable interrupts
	POP	ES DS	
	POP	02	

Adapter ROM

BIOS provides a method for integrating adapters with on-board ROM code into the system. During power-on self-test (POST), interrupt vectors are established for BIOS calls. When the default vectors are in place, a scan for adapter-ROM modules occurs. At this point, an adapter-ROM routine can gain control. The routine can establish or intercept interrupt vectors to hook into the system.

Early in POST, the absolute addresses hex C0000 through hex C7FFF are scanned in 2KB blocks to search for adapter-ROM modules that need to be initialized (for example, valid video adapter ROM).

Later in POST, the absolute addresses hex C8000 through hex DFFFF are scanned in 2KB blocks to search for devices with valid adapter-ROM modules. Valid adapter ROM is defined as follows:

- Byte 0: Hex 55
- Byte 1: Hex AA
- **Byte 2:** A length indicator, representing the number of 512-byte blocks (the limit is hex 7F) in the ROM (length divided by 512). A checksum tests the integrity of the ROM module. Each byte in the defined ROM is summed modulo hex 100. This sum must be 0 for the module to be valid.

When POST identifies valid adapter ROM, it executes a far call to byte 3 of the ROM (which should contain executable code). The device can now perform power-on initialization. The adapter ROM should return control to POST by executing a far return.

For the PC Convertible, if the adapter ROM detects a self-test error, it should perform the following steps before returning:

- Set bit 4 of hex 40:12 (POST status) to 1.
- Set the device number for the supported adapter in (AH).
- Set a two-digit error code in (AL).

If no self-test error is found, the adapter ROM should reset bit 4 of hex 40:12 (POST status) to 0 before returning.

For Personal System/2 products with Micro Channel architecture, a video adapter in the channel has a ROM signature code that identifies it. During POST, when CMOS is not valid (abnormal condition), the signature code is used to find the first video adapter and set up its ROM programmable option select (POS) parameters.

The code starts at hex 0C in the ROM address space and consists of:

77H, CCH, 'VIDEO '

The POS parameters are accessed from offset hex 30 in the ROM address space and are in the following order:

POS Byte 102, POS Byte 103, POS Byte 104, POS Byte 105

Video ROM scan remains from hex C0000 to hex C7FFF.

For Personal System/2 BIOS dated 10/7/87 and later, the adapter-ROM integration method is as follows:

Early in POST, the absolute addresses hex C0000 through DFFFF are scanned in 2KB blocks to search for adapter-ROM modules that have video-adapter signature code, as previously described. Only adapters with a video signature code are initialized early in POST.

Later in POST, the absolute addresses hex C0000 through DFFFF are scanned in 2KB blocks to initialize other adapter-ROM modules that were not initialized in the early scan.

For the PC Convertible, during early ROM scan, the following protocol is established to determine the video support:

On return from a call to a video-adapter-ROM module, (BH) indicates the following:

(BH) = 00H -	Not a video adapter
≖ 02H -	Video adapter supporting video in the
	color/graphics adapter range
= 04H -	Video adapter supporting video in the
	monochrome adapter range

Video-Function Compatibility

The following procedures are recommended to provide video-function compatibility for application software.

Video-Presence Test

Use this video-presence test to determine which IBM video functions are present.

 Issue Interrupt 10H, Read/Write Display-Combination Code function with ((AH) = 1AH), Read Display-Combination Code ((AL) = 00H).

On return, if the value of (AL) is not hex 1A, the Read/Write Display-Combination Code function is not supported, and step 2 should be followed to determine video presence.

On return, if the value of (AL) is hex 1A, the information that is returned in (BX) defines the video environment. The active display code is returned in (BL). The alternative display code, if any, is returned in (BH). Refer to Interrupt 10H, Read/Write Display-Combination Code function ((AH) = 1AH) for display-code definitions.

 To determine the presence of an IBM Enhanced Graphics Adapter (EGA) when the Read/Write Display-Combination Code function is not supported, issue Interrupt 10H, Alternative Selection function ((AH) = 12H), Return EGA Information ((BL) = 10H).

On return, if the value of (BL) is hex 10, an EGA is not present, and step 3 should be followed.

On return, if the value of (BL) is not hex 10, an EGA is present. Note that an IBM Color/Graphics Monitor Adapter or an IBM Monochrome Display and Printer Adapter might also be present, depending on the EGA switch settings.

3. Complete steps 1 and 2 before performing this step. The video functions that might be present at this point are the IBM Color/Graphics Monitor Adapter, the IBM Monochrome Display and Printer Adapter, or both. Perform a presence test on video buffer addresses hex 0B8000 and hex 0B0000 to determine which video functions are present.

Video-Mode Switching

Use the following video-mode switching procedure when applications will switch between monochrome and color video modes. A correct video-presence test, as previously described, is required. The following three system-video environments are possible:

- A single video function that supports either monochrome or color video modes. If a monochrome function is present, only monochrome video modes are available. If a color function is present, only color video modes are available.
- Two video functions, one supporting color video modes, and the other supporting monochrome video modes. In this case, both monochrome and color video modes are available. To switch from monochrome to color or from color to monochrome, the application program must change bits 5 and 4 (video mode type) of data area hex 40:10 to monochrome or color and issue Interrupt 10H, Set Mode function ((AH) = 00H).
- A single video function that supports both monochrome and color video modes. To determine whether a single video function supports both monochrome and color video modes, the application program should issue Interrupt 10H, Return Functionality/State Information function ((AH) = 1BH).

On return, if the value of (AL) is not hex 1B, the Return Functionality/State Information function is not supported, and support for both monochrome and color video modes on a single video function is not available.

On return, if the value of (AL) is hex 1BH, use the returned information to determine whether bit 0 (all modes on all displays active) of byte (DI+2DH) is set to 1. If it is set to 1, both monochrome and color modes are available, and the application program should change the video-modes bits for monochrome or color and issue Interrupt 10H, Set Mode function ((AH) = 00H). If it is set to 0, only monochrome modes or color modes are available, depending on the results of the video-presence test.

Multitasking Provisions

BIOS provides hooks to assist in multitasking information. Whenever a Busy (Wait) loop occurs in BIOS, a hook is provided for the program to break out of the loop. Also, when BIOS services an interrupt, a corresponding Wait loop is ended, and another hook is provided. A program can be written that employs most of the device-driver code. The following information is valid only in the microprocessor real-address mode, and the code must use the following procedures to enable this support.

The program is responsible for matching corresponding Wait and Post calls and for the serialization of access to the device driver. The BIOS code is not reentrant.

The multitasking dispatcher uses the following four interfaces:

Startup: The startup code hooks Interrupt 15H. The dispatcher is responsible for checking for function codes (AH) = 90H and (AH) = 91H (see the following descriptions of Wait and Post). The dispatcher must pass all other functions to the previous user of Interrupt 15H (use a JMP or CALL instruction). If the value of (AH) is hex 90 or hex 91, the dispatcher must perform the appropriate processing and return by the IRET instruction.

Serialization: The multitasking system must ensure that the device driver code is used serially. Multiple entries into the code can result in errors.

Wait (Busy): When BIOS is about to enter a Wait loop, it first issues Interrupt 15H, (AH) = 90H. This signals a Wait condition. At this point, the dispatcher should save the task status and dispatch another task. This enables overlapped execution of tasks when the hardware is busy. The following is an outline of the code that has been added to BIOS to perform this function.

MOV AX, 90xxH	;Wait code in AH and
	; type code in AL
INT 15H	;Issue call
JC TIMEOUT	;Optional: for time-out or
	; if carry is set, time-out
	; occurred
NORMAL TIMEOUT LOGIC	;Normal time-out

Post (Interrupt): When BIOS has set an interrupt flag for a corresponding Busy loop, it issues Interrupt 15H, (AH) = 91H. This signals a Post condition. At this point, the dispatcher must set the task status to "ready to run" and return to the interrupt routine. The following is an outline of the code that has been added to BIOS to perform this function.

MOV AX, 91xxH	;Post code AH and
	; type code AL
INT 15H	;Issue call

Three Wait loop function-code classes are supported:

- The first (hex 0 to hex 7F) is serially reusable. This means that for devices that use these codes, access to BIOS must be restricted to one task at a time, and the operating system must serialize access.
- The second (hex 80 to hex BF) is for reentrant devices. There is no restriction on the number of tasks that can use a device. (ES:BX) is used to distinguish between different calls.
- The third (hex C0 to hex FF) is noninterrupt (wait-only calls). There is no corresponding interrupt for the Wait loop. The dispatcher must take the appropriate action to satisfy this condition and exit from the loop. There is no complementary Post for these Wait conditions. They are time-out only, and the times are function-number dependent.

To support time-outs properly, the multitasking dispatcher must be aware of time. If a device enters a Busy loop, generally, it should remain there for a specific length of time before indicating an error. The dispatcher must return to the BIOS Wait loop with the carry flag set to 1 if a time-out occurs.

Application Guidelines

Use the following information to develop application programs for IBM Personal System/2 and Personal Computer products. Whenever possible, BIOS should be used as an interface to hardware to provide maximum compatibility and portability of applications across systems.

Math-Coprocessor Testing

Interrupt 11H (Equipment Determination) should be used where possible as the method for detecting the presence of the math coprocessor.

Hardware Interrupts

Hardware interrupts are level sensitive for systems that use the Micro Channel architecture; hardware interrupts are edge triggered for systems that use the PC-type I/O channel. In edge-triggered-interrupt systems, the interrupt controller clears its internal 'interrupt in progress' latch when the interrupt routine sends an End of Interrupt (EOI) command to the controller. The EOI command is sent, regardless of whether the incoming interrupt request to the controller is active or inactive.

In level-sensitive-interrupt systems, the 'interrupt in progress' latch is readable at an I/O-address bit position. This latch is read during the Interrupt Service routine; it can be reset by the read operation, or it might require an explicit reset.

Note: For performance and latency considerations, designers might want to limit the number of devices that share an interrupt level.

The interrupt controller on level-sensitive interrupt systems requires the interrupt request to be inactive at the time the EOI command is sent; otherwise, a "new" interrupt request will be detected, and another microprocessor interrupt will be caused.

To avoid this problem, a level-sensitive interrupt handler must clear the interrupt condition, usually by a Read or Write command to an I/O port on the device that is causing the interrupt.

| Because of the speed of the processor, a delay must be added after | every repetitive I/O operation to a controller or device to ensure that | I/O operations are synchronized with the processor. The JMP \$+2 | instruction is not recommended for this purpose.

Before the interrupt controllers are programmed, interrupts should be
disabled through a Clear Interrupt Flag (CLI) instruction. This
includes programming of the Mask register and issuing EOI
instructions, initialization-command bytes, and operation-command
bytes.

In level-sensitive-interrupt systems, hardware prevents the interrupt controllers from being set to the edge-triggered mode.

Hardware interrupt IRQ 9 is defined as the replacement interrupt level for the cascade level IRQ 2. Program interrupt sharing should be implemented on IRQ 2, Interrupt 0AH. The following processing occurs to maintain compatibility with the IRQ 2 that is used by IBM Personal Computer products:

- 1. A device drives the interrupt request that is active on IRQ 2 of the channel.
- 2. This interrupt request is mapped in hardware to IRQ 9 input on the slave interrupt controller.
- 3. When the interrupt occurs, the system microprocessor passes control to the IRQ 9 (Interrupt 71H) interrupt handler.
- 4. This interrupt handler sends an EOI command to the slave interrupt controller and passes control to the IRQ 2 (Interrupt 0AH) interrupt handler.
- 5. When handling the interrupt, the IRQ 2 interrupt handler causes the device to reset the interrupt request before sending an EOI command to the master interrupt controller that finishes servicing the IRQ 2 request.

Programming Considerations

The IBM-supported languages of IBM C, BASIC, FORTRAN, COBOL, and Pascal are the best choices for writing compatible programs. If a program uses specific features of the hardware, the program might not be compatible with all IBM Personal System/2 and Personal Computer products.

Any program that requires precise timing information should obtain it through an operating system or language interface (for example, TIME\$ in BASIC). The use of programming loops can prevent a

program from being compatible with other Personal System/2 and IBM Personal Computer products and software.

BIOS and Operating-System Function Calls

For maximum portability, programs should perform all I/O operations through operating-system function calls. In environments where the operating system does not provide the necessary programming interfaces, programs should access the hardware through BIOS function calls, if it is permissible. When writing programs, consider the following:

- In some environments, program interrupts are used for access to these functions. This practice removes the absolute addressing from the program. Only the interrupt number is required.
- The system can mask hardware sensitivity. New devices can change BIOS to accept the same programming interface on the new device.
- When BIOS provides parameter tables, such as for video or diskette, a program can substitute new parameter values by building a new copy of the table and changing the vector to point to that table. The program should copy the current table, using the current vector, and then modify those locations in the table that need to be changed. In this way, the program does not inadvertently change any values that should be left the same.
- The diskette parameters table that is pointed to by Interrupt 1EH consists of 11 parameters that are required for diskette operation. It is recommended that the values that are supplied in ROM be used. If it becomes necessary to modify any of the parameters, build another parameter block, and modify the address at interrupt 1EH (hex 00:78) to point to the new block.

The parameters were established to allow:

- Some models of the IBM Personal Computer to operate both the 5.25-inch high-capacity diskette drive (96 tracks per inch) and the 5.25-inch double-sided diskette drive (48 tracks per inch)
- Some models of the Personal System/2 system to operate both the 3.5-inch 1.44MB diskette drive and the 3.5-inch 720KB diskette drive.

The Gap Length parameter is not always retrieved from the parameter block. The gap length that is used during diskette read, write, and verify operations is derived from within diskette BIOS. The gap length for format operations is still obtained from the parameter block.

If a parameter block contains a Head Settle Time parameter value of 0 milliseconds, BIOS enforces a minimum head settle time of 15 milliseconds. Read and verify operations use the head settle time that is provided by the parameter block.

1

For any function that requires a parameter block that contains a Motor Start Wait parameter of less than 500 milliseconds (1 second for a Personal Computer product), diskette BIOS enforces a minimum time of 500 milliseconds (1 second for a Personal Computer product).

- Programs can be designed to reside on both 5.25-inch and 3.5-inch diskettes. Because not all programs are operating-system dependent, the following procedure can be used to determine which type of media is in a diskette drive:
 - 1. Verify track 0, head 0, sector 1 (1 sector). This enables diskette BIOS to determine whether the format of the media is a recognizable type.

If the verify operation fails, issue the Reset function ((AH) = 00H) to diskette BIOS and try the operation again. If it fails again, the media needs to be formatted or is defective.

2. Verify track 0, head 0, sector 16 (1 sector).

If the verify operation fails, either a 5.25-inch (48 TPI) or a 3.5-inch 720KB diskette is installed. To determine the type, verify track 78, head 1, sector 1 (1 sector). A successful verification of track 78 indicates that a 3.5-inch 720KB diskette is installed; a failed verification indicates that a 5.25-inch (48 TPI) diskette is installed.

- **Note:** Refer to the *DOS Technical Reference* for the file-allocation-table parameters for single-sided and double-sided diskettes.
- 3. Read the diskette-controller status in BIOS, starting with address hex 40:42. The fifth byte defines the head that the operation ended with. If the operation ended with head 1, the diskette is a 5.25-inch high-capacity (96 TPI) diskette; if the operation ended with head 0, the diskette is a 3.5-inch 1.44MB diskette.
- Newer Personal System/2 products might support Interrupt 13H—Diskette, Get Media Type function ((AH) = 20H).

Section 6. System Identification

Each BIOS ROM module has a model byte at address hex F000:FFFE in ROM. In some cases, a submodel byte and a BIOS revision-level byte are used to further distinguish between the various BIOS ROM modules. To gain access to this information, see Interrupt 15H, Return System Configuration Parameters function ((AH) = C0H).

A model byte changes when there are major processing-unit architecture changes. For example, 80286-based systems have model byte hex FC and have the following additional features:

- Protected virtual address mode
- 24 bits of addressing.

| The 80386- and 80486-based systems have model byte hex F8 and | have the following additional features:

- 32-bit registers
- 32-bit addressing
- 32-bit flat model mode
- Virtual 8086 mode.

A submodel byte changes when a system implements a
 software-detectable change from previous systems with the same
 model byte.

A BIOS revision level changes when the ROM image changes for a model or submodel.

The following table lists the system-identification information for Personal Computer and Personal System/2 products.

Product	BIOS Date	Modei Byte	Submodel Byte	Revision
PC	4/24/81	FF	00	00
PC	10/19/81	FF	00	00 01
PC	10/27/82	FF	00	02
PC/XT	11/8/82	FE	00	00
PC/XT	1/10/86	FB	00	01
PC/XT	5/9/86	FB	00	02
PC <i>jr</i>	6/1/83	FD	00	00

Figure 6-1 (Part 1 of 3). System Identification

	BIOS	Model	Submodel	
Product	Date	Byte	Byte	Revision
AT	1/10/84	FC	00	00
AT	6/10/85	FC	00	01
AT	11/15/85	FC	01	00
PC/XT Model 286	4/21/86	FC	02	00
PC Convertible	9/13/85	F9	00	00
PS/2 Model 25	6/26/87	FA	01	00
PS/2 Model 25	11/2/88	FA	01	01
PS/2 Model 30	9/2/86	FA	00	00
PS/2 Model 30	1/31/89	FA	00	04
PS/2 Model 30 286	8/25/88	FC	09	00
PS/2 Model 30 286	11/30/88	FC	09	01
PS/2 Model 30 286	5/30/89	FC	09	02
PS/2 Model 30 286		FC	09	03
PS/2 Model 40 SX/35 SX	3/15/91	F8	19	05
PS/2 Model 40 SX/35 SX	4/4/91	F8	19	06
PS/2 Model 40 SX/35 SX	6/4/91	F8	19	07
PS/2 Model L40 SX		F8	23	00
PS/2 Model 50 (Type 1)	2/13/87	FC	04	00
PS/2 Model 50		FC	04	01
PS/2 Model 50 (Type 1)	11/2/89	FC	04	02
PS/2 Model 50 (Type 2)	1/28/88	FC	04	03
PS/2 Model 50	5/12/88	FC	04	04
PS/2 Model 55 SX	11/2/88	F8	0C	00
PS/2 Model 55 SX		F8	0C	01
PS/2 Model 55 LS	2/8/90	F8	1E	00
PS/2 Model 57 SX	5/10/91	F8	26	00
PS/2 Model 60	2/13/87	FC	05	00
PS/2 Model 65 SX	2/8/90	F8	1C	00
PS/2 Model 70 (Type 2)	4/11/88	F8	04	02
PS/2 Model 70	3/17/89	F8	04	03
PS/2 Model 70	12/15/89	F8	04	04
PS/2 Model 70 (Type 1)	4/11/88	F8	09	02
PS/2 Model 70	3/17/89	F8	09	03
PS/2 Model 70	12/15/89	F8	09	04
PS/2 Model 70 (Type 3)	6/8/88	F8	0D	00
PS/2 Model 70	2/20/88	F8	0D	01
PS/2 Model 70 486 (Type 4)	12/1/89	F8	1B	00
PS/2 Model P70		F8	0B	00
PS/2 Model P70		F8	0B	02
PS/2 Model 80 (Type 1)	3/30/87	F8	00	00
PS/2 Model 80		F8	00	01
PS/2 Model 80	6/19/89	F8	00	02
PS/2 Model 80 (Type 2)	10/7/87	F8	01	00
PS/2 Model 80	11/21/89	F8	80	01
PS/2 Model 80	2/15/90	F8	80	02

| Figure 6-1 (Part 2 of 3). System Identification

Product	BIOS Date	Model Byte	Submodel Byte	Revision
PS/2 Model 90 (Type 1)	10/1/90	F8	11	00
PS/2 Model 90 (Type 2)	10/1/90	F8	13	00
PS/2 Model 90 (Type 3)	4/24/91	F8	2D	01
PS/2 Model 90 (Type 3)	4/24/91	F8	2F	01
PS/2 Model 95 (Type 1)	10/1/90	F8	14	00
PS/2 Model 95 (Type 2)	10/1/90	F8	16	00
PS/2 Model 95 (Type 3)	4/24/91	F8	2C	01
PS/2 Model 95 (Type 3)	4/24/91	F8	2E	01

Figure 6-1 (Part 3 of 3). System Identification

Note: Information about a specific system board can be found in the technical reference for that model.

Notes:

Section 7. Scan Code/Character Code Combinations

Note: For scan code/character code combinations for the PC Space Saving (84-/85-key) Keyboard, refer to the Personal System/2 Model 25 Technical Reference or the "Keyboards" section of the Personal System/2 Hardware Interface Technical Reference—Common Interfaces.

The Keyboard Read function ((AH) = 00H) and the Keyboard Status function ((AH) = 01H) of Interrupt 16H apply to the 83-/84-key keyboard, the 101-/102-key keyboard (standard and extended function), and the 122-key keyboard. However, these functions return only the scan code/character code combinations that are supported by the 83-/84-key keyboard and the 101-/102-key standard-function keyboard.

The Extended-Keyboard Read function ((AH) = 10H) and the Extended Keystroke Status function ((AH) = 11H) apply to the 83-/84-key keyboard, the 101-/102-key keyboard (standard and extended function), and the 122-key keyboard. However, these functions return only the scan code/character code combinations that are supported by the 101-/102-key extended-function keyboard.

The Keyboard Read for the 122-Key Keyboard function ((AH) = 20H)
and the Keystroke Status for the 122-Key Keyboard function
((AH) = 21H) apply to the 83-/84-key keyboard, the 101-/102-key
keyboard (standard and extended function), and the 122-key
keyboard. See the table on page 7-13 for the additional keystrokes
and scan code/character code combinations that are supported by the
122-key keyboard.

The following table lists the keyboard keystrokes and the scan code/character code combinations that are returned through Interrupt 16H.

	83-/84-Key	101-/102-Key	101-/102-Key	
	Standard	Standard	Extended	
Keystroke	Function	Function	Function	
Esc	01/1B	01/1B	01/1B	
1	02/31	02/31	02/31	
2	03/32	03/32	03/32	
3	04/33	04/33	04/33	
4	05/34	05/34	05/34	
5	06/35	06/35	06/35	
6	07/36	07/36	07/36	
7	08/37	08/37	08/37	
8	09/38	09/38	09/38	
9	0A/39	0A/39	0A/39	
0	0B/30	0B/30	0B/30	
-	0C/2D	0C/2D	0C/2D	
=	0D/3D	0D/3D	0D/3D	
Backspace	0E/08	0E/08	0E/08	
Tab	0F/09	0F/09	0F/09	
q	10/71	10/71	10/71	
ŵ	11/77	11/77	11/77	
e	12/65	12/65	12/65	
r	13/72	13/72	13/72	
t	14/74	14/74	14/74	
y	15/79	15/79	15/79	
u u	16/75	16/75	16/75	
i	17/69	17/69	17/69	
0	18/6F	18/6F	18/6F	
p	19/70	19/70	19/70	
ĺ	1A/5B	1A/5B	1A/5B	
j	1B/5D	1B/5D	1B/5D	
Return	1C/0D	1C/0D	1C/0D	
Ctrl	**	**	**	
a	1E/61	1E/61	1E/61	
s	1F/73	1F/73	1F/73	
d	20/64	20/64	20/64	
f	21/66	21/66	21/66	

Figure 7-1 (Part 1 of 3). Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
g h	22/67	22/67	22/67
	23/68	23/68	23/68
j	24/6A	24/6A	24/6A
k	25/6B	25/6B	25/6B
I	26/6C	26/6C	26/6C
;	27/3B	27/3B	27/3B
,	28/27	28/27	28/27
•	29/60	29/60	29/60
Shift	**	**	**
1	2B/5C	2B/5C	2B/5C
Z	2C/7A	2C/7A	2C/7A
x	2D/78	2D/78	2D/78
C	2E/63	2E/63	2E/63
v	2F/76	2F/76	2F/76
b	30/62	30/62	30/62
n	31/6E	31/6E	31/6E
m	32/6D	32/6D	32/6D
,	33/2C	33/2C	33/2C
	34/2E	34/2E	34/2E
1	35/2F	35/2F	35/2F
*	37/2A	37/2A	37/2A
Alt	**	**	**
Space	39/20	39/20	39/20
Caps Lock	**	**	**
F1	3B/00	3B/00	3B/00
F2	3C/00	3C/00	3C/00
F3	3D/00	3D/00	3D/00
F4	3E/00	3E/00	3E/00
F5	3F/00	3F/00	3F/00
F6	40/00	40/00	40/00
F7	41/00	41/00	41/00
F8	42/00	42/00	42/00
F9	43/00	43/00	43/00

Figure 7-1 (Part 2 of 3). Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
F10	44/00	44/00	44/00
F11	(no key)		85/00
F12	(no key)		86/00
Num Lock	**	**	**
Scroll Lock	**	**	**
Home	47/00	47/00	47/00
Up Arrow	48/00	48/00	48/00
PgUp	49/00	49/00	49/00
-	4A/2D	4A/2D	4A/2D
Left Arrow	4B/00	4B/00	4B/00
Center Key			4C/00
Right Arrow	4D/00	4D/00	4D/00
+	4E/2B	4E/2B	4E/2B
End	4F/00	4F/00	4F/00
Down Arrow	50/00	50/00	50/00
PgDn	51/00	51/00	51/00
Ins	52/00	52/00	52/00
Del	53/00	53/00	53/00
SysRq	**	(no key)	(no key)
Key 45	(no key)	56/5C	56/5C
Enter	(no key)	1C/0D	E0/0D
1	(no key)	35/2F	E0/2F
PrtSc	(no key)	**	**
Pause	(no key)	**	**
Home	(no key)	47/00	47/E0
Up Arrow	(no key)	48/00	48/E0
PageUp	(no key)	49/00	49/E0
Left Arrow	(no key)	4B/00	4B/E0
Right Arrow	(no key)	4D/00	4D/E0
End	(no key)	4F/00	4F/E0
Down Arrow	(no key)	50/00	50/E0
PageDown	(no key)	51/00	51/E0
Insert	(no key)	52/00	52/E0
Delete	(no key)	53/00	53/00

Figure 7-1 (Part 3 of 3). Keyboard Keystrokes

The following table lists the Shift keyboard keystrokes and the scan code/character code combinations that are returned through Interrupt 16H.

	83-/84-Key Standard	101-/102-Key Standard	101-/102-Key Extended
Keystroke	Function	Function	Function
Shift Esc	01/1B	01/1B	01/1B
Shift !	02/21	02/21	02/21
Shift @	03/40	03/40	03/40
Shift #	04/23	04/23	04/23
Shift \$	05/24	05/24	05/24
Shift %	06/25	06/25	06/25
Shift 🔨	07/5E	07/5E	07/5E
Shift &	08/26	08/26	08/26
Shift *	09/2A	09/2A	09/2A
Shift (0A/28	0A/28	0A/28
Shift)	0B/29	0B/29	0B/29
Shift _	0C/5F	0C/5F	0C/5F
Shift +	0D/2B	0D/2B	0D/2B
Shift Backspace	0E/08	0E/08	0E/08
Shift Tab (Backtab)	0F/00	0F/00	0F/00
Shift Q	10/51	10/51	10/51
Shift W	11/57	11/57	11/57
Shift E	12/45	12/45	12/45
Shift R	13/52	13/52	13/52
Shift T	14/54	14/54	14/54
Shift Y	15/59	15/59	15/59
Shift U	16/55	16/55	16/55
Shift I	17/49	17/49	17/49
Shift O	18/4F	18/4F	18/4F
Shift P	19/50	19/50	19/50
Shift {	1A/7B	1A/7B	1A/7B
Shift }	1B/7D	1B/7D	1B/7D
Shift Return	1C/0D	1C/0D	1C/0D
Shift Ctrl	**	**	**
Shift A	1E/41	1E/41	1E/41
Shift S	1F/53	1F/53	1F/53
Shift D	20/44	20/44	20/44
Shift F	21/46	21/46	21/46
Shift G	22/47	22/47	22/47
Shift H	23/48	23/48	23/48
Shift J	24/4A	24/4A	24/4A
Shift K	25/4B	25/4B	25/4B
Shift L	26/4C	26/4C	26/4C
Shift :	27/3A	27/3A	27/3A
Shift "	28/22	28/22	28/22
Shift ~	29/7E	29/7E	29/7E

Figure 7-2 (Part 1 of 3). Shift Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard	101-/102-Key Extended
VAARLOKA	runction	Function	Function
Shift ¦	2B/7C	2B/7C	2B/7C
Shift Z	2C/5A	2C/5A	2C/5A
Shift X	2D/58	2D/58	2D/58
Shift C	2E/43	2E/43	2E/43
Shift V	2F/56	2F/56	2F/56
Shift B	30/42	30/42	30/42
Shift N	31/4E	31/4E	31/4E
Shift M	32/4D	32/4D	32/4D
Shift <	33/3C	33/3C	33/3C
Shift >	34/3E	34/3E	34/3E
Shift ?	35/3F	35/3F	35/3F
Shift *	37/2A	37/2A	37/2A
Shift Alt	**	**	**
Shift Space	39/20	39/20	39/20
Shift Caps Lock	**	**	**
Shift F1	54/00	54/00	54/00
Shift F2	55/00	55/00	55/00
Shift F3	56/00	56/00	56/00
Shift F4	57/00	57/00	57/00
Shift F5	58/00	58/00	58/00
Shift F6	59/00	59/00	59/00
Shift F7	5A/00	5A/00	5A/00
Shift F8	5B/00	5B/00	5B/00
Shift F9	5C/00	5C/00	5C/00
Shift F10	5D/00	5D/00	5D/00
Shift F11	(no key)		87/00
Shift F12	(no key)		88/00
Shift Num Lock	(110 KOY) **	**	**
Shift Scroll Lock	**	**	**
Shift 7	47/37	47/37	47/37
Shift 8	48/38	48/38	48/38
Shift 9	49/39	49/39	40/30
Shift -	48/39 4A/2D	49/39 4A/2D	
Shift 4	4B/34	4R/2D 4B/34	4A/2D
Shift 5	4D/34 4C/35	4B/34 4C/35	4B/34
Shift 6	4D/36	40/35 4D/36	4C/35 4D/36
Shift +	4E/2B	4D/36 4E/2B	
Shift 1	4E/2B 4F/31	4E/2B 4F/31	4E/2B
Shift 2	50/32	4F/31 50/32	4F/31
Shift 3	51/33	51/33	50/32
Shift 0	52/30	52/30	51/33
Shift .	53/2E	52/30 53/2E	52/30 52/35
Shift SysRq	00/2C		53/2E
Shift Key 45	(no kov)	(no key)	(no key)
Shift Enter	(no key)	56/7C	56/7C
Shift /	(no key)	1C/0D	E0/0D
Sint /	(no key)	35/2F	E0/2F

Figure 7-2 (Part 2 of 3). Shift Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
	<i>,</i>	**	**
Shift PrtSc	(no key)	**	**
Shift Pause	(no key)	**	**
Shift Home	(no key)	47/00	47/E0
Shift Up Arrow	(no key)	48/00	48/E0
Shift PgUp	(no key)	49/00	49/E0
Shift Left Arrow	(no key)	4B/00	4B/E0
Shift Right	(no key)	4D/00	4D/E0
Shift End	(no key)	4F/00	4F/E0
Shift Down Arrow	(no key)	50/00	50/E0
Shift PgDn	(no key)	51/00	51/E0
Shift Insert	(no key)	52/00	52/E0
Shift Delete	(no key)	53/00	53/E0
currently running, into the Interrupt 10	but they perform sor	eystroke for the applicant ne other action. They a and are ignored.	

Figure 7-2 (Part 3 of 3). Shift Keyboard Keystrokes

The following table lists the Ctrl keyboard keystrokes and the scan code/character code combinations that are returned through Interrupt 16H.

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
Ctrl Esc	01/1B	01/1B	01/1B
Ctrl 1			
Ctrl 2 (NUL)	03/00	03/00	03/00
Ctrl 3			
Ctri 4			
Ctrl 5			
Ctrl 6 (RS)	07/1E	07/1E	07/1E
Ctrl 7			
Ctrl 8			
Ctrl 9			
Ctrl 0			
Ctrl _	0C/1F	0C/1F	0C/1F
Ctrl =			
Ctrl Backspace (DEL)	0E/7F	0E/7F	0E/7F
Ctrl Tab			94/00

Figure 7-3 (Part 1 of 3). Ctrl Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
Ctri g (DC1)	10/11	10/11	10/11
Ctrl w (ETB)	11/17	11/17	11/17
Ctrl e (ENQ)	12/05	12/05	12/05
Ctrl r (DC2)	13/12	13/12	13/12
Ctri t (DC4)	14/14	14/14	14/14
Ctrl y (EM)	15/19	15/19	15/19
Ctrl u (NAK)	16/15	16/15	16/15
Ctrl i (HT)	17/09	17/09	17/09
Ctrl o (SI)	18/0F	18/0F	18/0F
Ctrl p (DLE)	19/10	19/10	19/10
Ctrl [(ESC)	1A/1B	1A/1B	1A/1B
Ctrl] (GS)	1B/1D	1B/1D	1B/1D
Ctrl Return (LF)	1C/0A	1C/0A	1C/0A
Ctrl a (SOH)	1E/01	1E/01	1E/01
Ctrl s (DC3)	1F/13	1F/13	1F/13
Ctrl d (EOT)	20/04	20/04	20/04
Ctrl f (ACK)	21/06	21/06	20/04 21/06
Ctrl g (BEL)	22/07	22/07	22/07
Ctrl h (Backspace)	23/08	23/08	23/08
Ctrl j (LF)	23/08 24/0A	23/08 24/0A	23/08 24/0A
Ctrl k (VT)	25/0B	24/0A 25/0B	
Ctri I (FF)	26/0C	25/0B 26/0C	25/0B
Ctrl;	20/00		26/0C
Ctrl			
Ctrl '			
Ctrl Shift	 **		
Ctrl \ (FS)	2B/1C	2B/1C	
Ctrl z (SUB)	2C/1A		2B/1C
Ctrl x (CAN)	2D/18	2C/1A	2C/1A
Ctri c (ETX)	2E/03	2D/18	2D/18
Ctrl v (SYN)	2E/03 2F/16	2E/03	2E/03
Ctrl b (STX)	30/02	2F/16	2F/16
Ctrl n (SO)	30/02 31/0E	30/02	30/02
Ctrl m (CR)	* · · · + =	31/0E	31/0E
	32/0D	32/0D	32/0D
Ctri,			
Ctrl .			
Ctrl / Ctrl *			
Ctrl Alt	**		96/00
Ctrl Alt Ctrl Space			
Ctrl Space Ctrl Caps Lock	39/20	39/20	39/20
Ctrl F1			
Ctrl F2	5E/00	5E/00	5E/00
Ctrl F3	5F/00	5F/00	5F/00
Ctrl F3	60/00	60/00	60/00
Ctrl F5	61/00	61/00	61/00
	62/00	62/00	62/00

Figure 7-3 (Part 2 of 3). Ctrl Keyboard Keystrokes

Keystroke	83-/84-Køy Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
Ctrl F6	63/00	63/00	63/00
Ctrl F7	64/00	64/00	64/00
Ctrl F8	65/00	65/00	65/00
Ctrl F9	66/00	66/00	66/00
Ctrl F10	67/00	67/00	67/00
Ctrl F11	(no key)		89/00
Ctrl F12	(no key)		8A/00
Ctrl Num Lock			
Ctrl Scroll Lock			
Ctrl Home	77/00	77/00	77/00
Ctrl Up Arrow			8D/00
Ctrl PgUp	84/00	84/00	84/00
Ctrl Keypad -			8E/00
Ctrl Left Arrow	73/00	73/00	73/00
Ctrl Center			8F/00
Ctrl Right Arrow	74/00	74/00	74/00
Ctrl Keypad +			90/00
Ctrl End	75/00	75/00	75/00
Ctrl Down Arrow			91/00
Ctrl PgDn	76/00	76/00	76/00
Ctrl Ins			92/00
Ctrl Del			93/00
Ctrl SysRq	**	(no key)	(no key)
Ctrl Key 45	(no key)		
Ctrl Enter	(no key)	1C/0A	E0/0A
Ctrl /	(no key)		95/00
Ctrl PrtSc	(no key)	72/00	72/00
Ctrl Break	(no key)	00/00	00/00
Ctrl Home	(no key)	77/00	77/E0
Ctrl Up	(no key)		8D/E0
Ctrl PageUp	(no key)	84/00	84/E0
Ctrl Left	(no key)	73/00	73/E0
Ctrl Right	(no key)	74/00	74/E0
Ctrl End	(no key)	75/00	75/E0
Ctrl Down	(no key)		91/E0
Ctrl PageDown	(no key)	76/00	76/E0
Ctrl Insert	(no key)		92/E0
Ctrl Delete	(no key)		93/E0
currently running, into the Interrupt	, but they perform so	eystroke for the applic me other action. They and are ignored.	

Figure 7-3 (Part 3 of 3). Ctrl Keyboard Keystrokes

The following table lists the Alt keyboard keystrokes and the scan code/character code combinations that are returned through Interrupt 16H.

W	83-/84-Key Standard	101-/102-Key Standard	101-/102-Key Extended
Keystroke	Function	Function	Function
Alt Esc			01/00
Alt 1	78/00	78/00	78/00
Alt 2	79/00	79/00	79/00
Alt 3	7A/00	7A/00	7A/00
Alt 4	7B/00	7B/00	7B/00
Alt 5	7C/00	7C/00	7C/00
Alt 6	7D/00	7D/00	7D/00
Alt 7	7E/00	7E/00	7E/00
Alt 8	7F/00	7F/00	7F/00
Alt 9	80/00	80/00	80/00
Alt 0	81/00	81/00	81/00
Alt -	82/00	82/00	82/00
Alt =	83/00	83/00	83/00
Alt Backspace			0E/00
Alt Tab			A5/00
Alt q	10/00	10/00	10/00
Alt w	11/00	11/00	11/00
Alte	12/00	12/00	12/00
Altr	13/00	13/00	13/00
Altt	14/00	14/00	14/00
Alt y	15/00	15/00	15/00
Alt u	16/00	16/00	16/00
Alt i	17/00	17/00	17/00
Alto	18/00	18/00	18/00
Alt p	19/00	19/00	19/00
Alt [1A/00
Alt]			1B/00
Alt Return			1C/00
Alt Ctrl	**	**	**
Alta	1E/00	1E/00	1E/00
Alts	1F/00	1F/00	1F/00
Alt d	20/00	20/00	20/00
Alt f	21/00	21/00	21/00
Altg	22/00	22/00	22/00
Alth	23/00	23/00	23/00
Alt j	24/00	24/00	24/00
Alt k	25/00	25/00	25/00
Alt I	26/00	26/00	26/00
Alt;			27/00
Alt '			28/00
Alt '			29/00

Figure 7-4 (Part 1 of 3). Alt Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
Alt Shift	**	**	**
Alt			2B/00
Alt z	2C/00	2C/00	2C/00
Alt x	2D/00	2D/00	2D/00
Alt c	2E/00	2E/00	2E/00
Alt v	2F/00	2F/00	2F/00
Altb	30/00	30/00	30/00
Alt n	31/00	31/00	31/00
Alt m	32/00	32/00	32/00
Alt,			33/00
Alt.			34/00
Alt /			35/00
Alt *			37/00
Alt Space	39/20	39/20	39/20
Alt Caps Lock	**	**	**
Alt F1	68/00	68/00	68/00
Alt F2	69/00	69/00	69/00
Alt F3	6A/00	6A/00	6A/00
Alt F4	6B/00	6B/00	6B/00
Alt F5	6C/00	6C/00	6C/00
Alt F6	6D/00	6D/00	6D/00
Alt F7	6E/00	6E/00	6E/00
Alt F8	6F/00	6F/00	6F/00
Alt F9	70/00	70/00	70/00
Alt F10	71/00	71/00	71/00
Alt F11			8B/00
Alt F12	(no key)		8C/00
Alt Num Lock	(no key)	**	**
Alt Scroll Lock	**	**	**
Alt Keypad -			4A/00
Alt Keypad +			4E/00
Alt Keypad Numbers	#	#	#
Alt Del	 **		 (na kaw)
Alt SysRq		(no key)	(no key)
Alt Key 45	(no key)		
Alt Enter	(no key)		A6/00
Alt /			A4/00
Alt Print Screen	(no key)	**	**
Alt Pause	(no key)		
Alt Home	(no key)		97/00
Alt Up	(no key)		98/00
Alt PageUp	(no key)		99/00
Alt Left	(no key)		9B/00
Alt Right	(no key)		9D/00
Alt End	(no key)		9F/00
Alt Down	(no key)		A0/00

Figure 7-4 (Part 2 of 3). Alt Keyboard Keystrokes

Keystroke	83-/84-Key Standard Function	101-/102-Key Standard Function	101-/102-Key Extended Function
Alt PageDown	(no key)		A1/00
Alt Insert	(no key)		A2/00
Alt Delete	(no key)		A3/00
currently running into the Interrupt	ons do not provide a k), but they perform sor	eystroke for the applica ne other action. They a	

Figure 7-4 (Part 3 of 3). Alt Keyboard Keystrokes

Note: For all keyboards, the numeric keypad can be used in combination with the Alt key to type any ASCII character. The scan code (always 00) and character code are returned after the Alt key is released. For example, pressing the Alt key and keypad 1, then releasing the Alt key returns scan code/character code combination hex 00/01; pressing the Alt key and keypad 255, then releasing the Alt key returns scan code/character code combination hex 00/FF.

The following table lists the keyboard keystrokes and the scan code/character code combinations that the 122-keyboard supports in addition to those listed previously. The Keyboard Read for the 122-Key Keyboard function ((AH) = 20H) and the Keystroke Status for the 122-Key Keyboard function ((AH) = 21H) must be used to return scan code/character code combinations for these keystrokes.

Keystroke	122-Key Extended Extended Function	
F13	EC/00	
F14	ED/00	
F15	EE/00	
F16	EF/00	
F17	F4/00	
F18	F5/00	
F19	F6/00	
F20	F7/00	
F21	F8/00	
F22	F9/00	
F23	FA/00	
F24	C0/00	
PA1	E8/00	
EraseEOF	F0/00	
Clear	FB/00	
Shift F13	C1/00	
Shift F14	C3/00	
Shift F15	C4/00	
Shift F16	C5/00	
Shift F17	C6/00	
Shift F18	C7/00	
Shift F19	C8/00	
Shift F20	C9/00	
Shift F21	CA/00	
Shift F22	CB/00	
Shift F23	CC/00	
Shift F24	CD/00	
Shift PA1	E9/00	
Shift EraseEOF	F1/00	
Shift Clear	FB/00	
Ctrl F13	CE/00	
Ctrl F14	CF/00	
Ctrl F15	D0/00	
Ctrl F16	D1/00	
Ctrl F17	D2/00	
Ctrl F18	D3/00	
Ctrl F19	D4/00	
Ctrl F20	D5/00	
Ctrl F21	D6/00	
Ctrl F22	D7/00	
Ctrl F23	D8/00	

| Figure 7-5 (Part 1 of 2). Keyboard Keystrokes - 122-Key Keyboard

Keystroke	122-Key Extended Extended Function	
Ctrl F24	D9/00	
Ctrl PA1	EA/00	
Ctrl EraseEOF	F2/00	
Ctrl Clear	FC/00	
Alt F13	DA/00	
Atl F14	DB/00	
Alt F15	DC/00	
Alt F16	DD/00	
Alt F17	DE/00	
Alt F18	DF/00	
Alt F19	E2/00	
Alt F20	E3/00	
Alt F21	E4/00	
Alt F22	E5/00	
Alt F23	E6/00	
Alt F24	E7/00	
Alt PA1	EB/00	
Alt EraseEOF	F3/00	
Alt Clear	FD/00	

Figure 7-5 (Part 2 of 2). Keyboard Keystrokes - 122-Key Keyboard

| The following keys on the leftmost keypad of the 122-key keyboard do | not produce scan code/character code combinations:

- Attn
- CrSel
- ExSel
- Copy Play
- The two blank keys.